

ECEn 670

Homework Problem Set 4

Due at beginning of class, Thursday, October 22, 2009

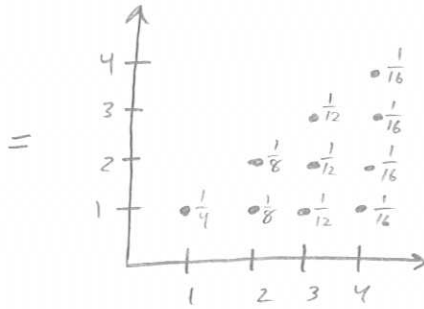
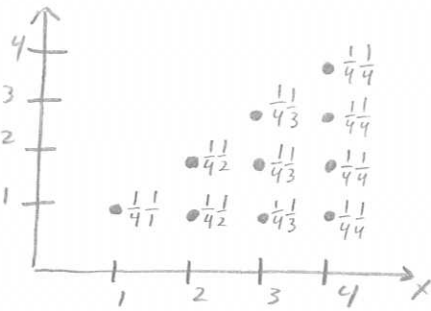
Problems are from *An Introduction to Statistical Signal Processing* by Gray and Davisson unless otherwise specified.

1. 4.1
2. 4.3
3. 4.5
4. 4.6
5. 4.7
6. ~~4.19~~
7. ~~4.22~~
8. ~~4.26~~
9. ~~4.29~~
10. ~~4.30~~
11. ~~4.31~~

$$4.1) P_X(k) = \begin{cases} 1/4, & x=1, 2, 3, 4 \\ 0, & \text{otherwise} \end{cases}$$

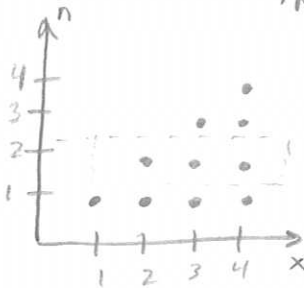
$$P_{N|X}(n|k) = \frac{1}{k}; n=1, 2, \dots, k.$$

$$a) P_{X,N}(x,n) = P_{N|X}(n|x) P_X(x)$$



$$b) P_N(n) = \begin{cases} \frac{1}{4} + \frac{1}{8} + \frac{1}{12} + \frac{1}{16}, & n=1 \\ \frac{1}{8} + \frac{1}{12} + \frac{1}{16}, & n=2 \\ \frac{1}{12} + \frac{1}{16}, & n=3 \\ \frac{1}{16}, & n=4 \\ 0, & \text{otherwise} \end{cases} = \begin{cases} \frac{25}{48}, & n=1 \\ \frac{13}{48}, & n=2 \\ \frac{7}{48}, & n=3 \\ \frac{1}{16}, & n=4 \\ 0, & \text{otherwise} \end{cases}$$

$$c) P_{X|N}(x|n) = \frac{P_{X,N}(x,n)}{P_N(n)}$$



$$P_{X|N}(x|2) = \begin{cases} \frac{1/8}{13/48}, & x=2 \\ \frac{1/12}{13/48}, & x=3 \\ \frac{1/16}{13/48}, & x=4 \\ 0, & \text{otherwise} \end{cases} = \begin{cases} \frac{6}{13}, & x=2 \\ \frac{4}{13}, & x=3 \\ \frac{3}{13}, & x=4 \\ 0, & \text{otherwise} \end{cases}$$

$P_N(2) = \frac{13}{48}$

$$d) P_{X|A} = \frac{P_{X,A}(x)}{P(A)} = \frac{P_{X,A}(x)}{\frac{1}{12} + \frac{1}{16} + \frac{1}{8} + \frac{1}{12} + \frac{1}{16}} = \frac{P_{X,A}(x)}{\frac{4+3+6+4+3}{48}} = \frac{P_{X,A}(x)}{\frac{20}{48}} = \frac{P_{X,A}(x)}{5/12}$$

$$P_{X|A}(x) = \begin{cases} \frac{1/8}{5/12}, & x=2 \\ \frac{1/12 + 1/12}{5/12}, & x=3 \\ \frac{1/16 + 1/16}{5/12}, & x=4 \\ 0, & \text{otherwise} \end{cases} = \begin{cases} \frac{3}{10}, & x=2 \\ \frac{2}{5}, & x=3 \\ \frac{3}{10}, & x=4 \\ 0, & \text{otherwise} \end{cases}$$

$$E[X|A] = 2\left(\frac{3}{10}\right) + 3\left(\frac{2}{5}\right) + 4\left(\frac{3}{10}\right) = \frac{3}{5} + \frac{6}{5} + \frac{6}{5} = \frac{15}{5} = \boxed{3}$$

$$E[X^2|A] = 4\left(\frac{3}{10}\right) + 9\left(\frac{2}{5}\right) + 16\left(\frac{3}{10}\right) = \frac{6}{5} + \frac{18}{5} + \frac{24}{5} = \frac{48}{5}$$

e) $E[C] = 3$ where C is cost of a book

$$T = \sum_{i=1}^n C_i \quad \text{since } T \text{ is total cost and } n \text{ is books bought}$$

$$E[T] \approx E[N]E[C] = \frac{7}{4} \cdot 3 = \boxed{\frac{21}{4}}$$

$$\text{var}(X^2|A) = E[X^2|A] - (E[X|A])^2 = \frac{48}{5} - 9 = \frac{48}{5} - \frac{45}{5} = \boxed{\frac{3}{5}}$$

$$\hookrightarrow E[N] = (1)\left(\frac{25}{48}\right) + (2)\left(\frac{13}{48}\right) + (3)\left(\frac{7}{48}\right) + (4)\left(\frac{1}{48}\right) = \frac{25}{48} + \frac{26}{48} + \frac{21}{48} + \frac{4}{48} = \frac{84}{48} = \frac{7}{4}$$

$$4.3) P_Z(k) = C \frac{a^k}{(1+a)^{k+1}}, k=0, 1, \dots$$

$$P_Z(k) \geq 0, \forall k \in \{0, 1, 2, \dots\} \Rightarrow C > 0$$

$$\begin{aligned} \sum_{k=0}^{\infty} P_Z(k) &= 1 = \sum_{k=0}^{\infty} C \frac{a^k}{(1+a)^{k+1}} \\ &= C \sum_{k=0}^{\infty} \frac{a^k}{(1+a)^{k+1}} \\ &= \frac{C}{1+a} \sum_{k=0}^{\infty} \left(\frac{a}{1+a}\right)^k \\ &= \frac{C}{1+a} \cdot \frac{1}{1 - \frac{a}{1+a}} \\ &= \frac{C}{1+a} \cdot \frac{1+a}{1+a-a} \\ &= C \end{aligned}$$

$$\therefore C = 1$$

$$\therefore P_Z(k) = \frac{a^k}{(1+a)^{k+1}}, k = \{0, 1, 2, \dots\}$$

$$E[Z] = \sum_{k=0}^{\infty} k \cdot \frac{a^k}{(1+a)^{k+1}}$$

$$= \frac{a}{(1+a)^2} \sum_{k=0}^{\infty} k \cdot \left(\frac{a}{1+a}\right)^{k-1}$$

$$= \frac{a}{(1+a)^2} \cdot \frac{1}{\left(1 - \frac{a}{1+a}\right)^2}$$

$$= \frac{a}{(1+a)^2} \cdot \frac{(1+a)^2}{(1+a-a)^2} = a \quad \therefore E[Z] = a$$

$$E[Z^2] = \sum_{k=0}^{\infty} k^2 \cdot \frac{a^k}{(1+a)^{k+1}}$$

$$= \frac{a^2}{(1+a)^3} \sum_{k=0}^{\infty} k^2 \cdot \left(\frac{a}{1+a}\right)^{k-2}$$

$$= \frac{a^2}{(1+a)^3} \cdot \left(\frac{2}{\left(1 - \frac{a}{1+a}\right)^3} + \frac{1+a}{a} \cdot \frac{1}{\left(1 - \frac{a}{1+a}\right)^2} \right)$$

$$= \frac{a^2}{(1+a)^3} \cdot \left(\frac{2(1+a)^3}{(1+a-a)^3} + \frac{(1+a)^3}{a(1+a-a)^2} \right) = 2a^2 + a$$

$$\text{Var}(Z) = E[Z^2] - (E[Z])^2 = 2a^2 + a - a^2 = \boxed{a^2 + a}$$

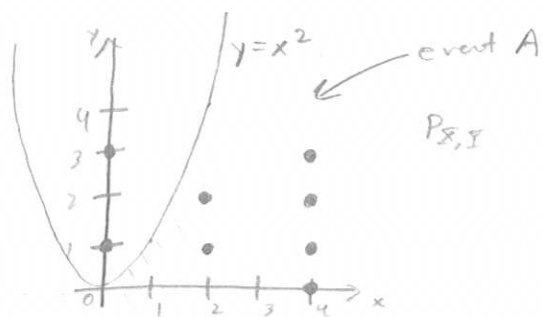
4.3 cont...)

$$\begin{aligned} E[e^{juz}] &= \sum_{z=0}^{\infty} e^{juz} p_z(z) \\ &= \sum_{z=0}^{\infty} e^{juz} \cdot \frac{a^z}{(1+a)^{z+1}} \\ &= \frac{1}{1+a} \sum_{z=0}^{\infty} \left(e^{ju} \cdot \frac{a}{1+a} \right)^z \end{aligned}$$

Note that $|e^{ju} \cdot \frac{a}{1+a}| = \left| \frac{a}{1+a} \right| < 1$, so

$$\begin{aligned} E[e^{juz}] &= \frac{1}{1+a} \cdot \frac{1}{1 - e^{ju} \frac{a}{1+a}} \\ &= \frac{1}{1+a} \cdot \frac{1+a}{1+a - ae^{ju}} \\ &= \frac{1}{1+a - ae^{ju}} \\ &= \frac{1}{1+a - a\cos(u) - j\sin(u)} \\ &= \frac{1+a - a\cos(u) + j\sin(u)}{(1+a - a\cos(u))^2 + a^2\sin^2(u)} \\ &= \frac{1+a(1-\cos(u))}{(1+a(1-\cos(u)))^2 + a^2\sin^2(u)} + j \cdot \frac{a\sin(u)}{(1+a(1-\cos(u)))^2 + a^2\sin^2(u)} \end{aligned}$$

4.5. Given the setup of Problem 3.10:



$$a) E[X] = \frac{1}{4}(0) + \frac{1}{4}(2) + \frac{1}{2}(4) = \frac{1}{2} + 2 = \frac{5}{2}$$

$$E[XY] = \frac{1}{8}(0+0+2+4+0+4+8+12) \\ = \frac{1}{8}(30) = \frac{30}{8} = \frac{15}{4}$$

$$b) E[Y|X=x] = \begin{cases} \frac{1}{2}(1+3) & , x=0 \\ \frac{1}{2}(1+2) & , x=2 \\ \frac{1}{4}(0+1+2+3) & , x=4 \end{cases} = \begin{cases} 2 & , x=0 \\ \frac{3}{2} & , x=2 \\ \frac{3}{2} & , x=4 \end{cases}$$

This is maximized for $x=0$.

c) A denotes event $X^2 \geq Y$

$$P(A) = P(\{(2,1), (2,2), (4,0), (4,1), (4,2), (4,3)\}) = \frac{6}{8} = \frac{3}{4}$$

$$E(XY|A) = \sum_{(x,y)} xy P_{XY|A}(x,y|A) = \frac{1/8}{3/4} (2+4+0+4+8+12) \\ = \frac{1}{6}(30) = \boxed{5}$$

4.6) X is R.V. with pdf $f_X(x)$ and c.f. $M_X(j\omega) = E[e^{j\omega X}]$

$$Y = aX + b \quad a, b > 0$$

Find pdf f_Y and c.f. $M_Y(j\omega)$ in terms of f_X , M_X

$$F_X(x) = P(X \leq x) = \int_{-\infty}^x f_X(x) dx$$

$$\begin{aligned} F_Y(y) &= P(Y \leq y) = P(aX + b \leq y) = P(aX \leq y - b) = P\left(X \leq \frac{y-b}{a}\right) \\ &= F_X\left(\frac{y-b}{a}\right) = \int_{-\infty}^{\frac{y-b}{a}} f_X(x) dx \end{aligned}$$

$$f_Y(y) = \frac{dF_Y(y)}{dy} = \frac{d}{dy} \int_{-\infty}^{\frac{y-b}{a}} f_X(x) dx = \boxed{\frac{1}{a} f_X\left(\frac{y-b}{a}\right)} \quad \text{Formula 3.41}$$

$$\begin{aligned} M_Y(j\omega) &= E[e^{j\omega Y}] = E[e^{j\omega(aX+b)}] = E[e^{j\omega a X} e^{j\omega b}] = e^{j\omega b} E[e^{j\omega a X}] \\ &= \underline{e^{j\omega b} M_X(j\omega a)} \end{aligned}$$

4.7) X, Y, Z are iid Gaussian with $N(1, 1)$

$$V = 2X + Y$$

$$W = 3X - 2Z + 5$$

$$\text{var}(X) = 1 = E[X^2] - (E[X])^2 = E[X^2] - 1$$

$$E[X^2] = 2$$

a) $E[VW] = E[(2X + Y)(3X - 2Z + 5)]$

$$= E[(6X^2 - 4XZ + 10X + 3XY - 2YZ + 5Y)]$$

$$= 6E[X^2] - 4E[X]E[Z] + 10E[X] + 3E[X]E[Y] - 2E[Y]E[Z] + 5E[Y]$$

$$= 6(2) - 4 + 10 + 3 - 2 + 5$$

$$= 12 + 12$$

$$= 24$$

b) The two parameters that completely specify $V+W$ are the mean and variance because they are Gaussian.

$$V+W = 2X + Y + 3X - 2Z + 5$$

$$= 5X + Y - 2Z + 5$$

$$E[V+W] = E[5X + Y - 2Z + 5] = 5E[X] + E[Y] - 2E[Z] + 5$$

$$= 5 + 1 - 2 + 5 = 9$$

$$\text{var}(V+W) = \text{var}(5X + Y - 2Z + 5) = 5^2 \text{var}(X) + \text{var}(Y) + 4 \text{var}(Z)$$

$$= 25 + 1 + 4 = 30$$

This is completely specified by mean of 9 and variance of 30.

c) Find c.f. of random vector $[V \ W]^t$

c.f. for Gaussian is

$$E[V] = 2E[X] + E[Y] - 2 + 1 = 3$$

$$E[W] = 3E[X] - 2E[Z] + 5 = 6$$

$$\text{var}(V) = 4 \text{var}(X) + \text{var}(Y) = 5$$

$$\text{var}(W) = 9 \text{var}(X) + 4 \text{var}(Z) = 13$$

$$\text{cov}(V, W) = E[VW] - E[V]E[W] = 24 - (3)(6) = 6$$

This is a cascade vector with $K_{(V,W)} = \begin{bmatrix} 5 & 6 \\ 6 & 13 \end{bmatrix}$ and $\vec{m} = \begin{bmatrix} 3 \\ 6 \end{bmatrix}$

$$M(\vec{u}) = e^{j\vec{u}^t \vec{m} - \vec{u}^t \Lambda \vec{u} / 2} \quad \text{where } \vec{m} = \begin{bmatrix} 3 \\ 6 \end{bmatrix} \text{ and } \Lambda = \begin{bmatrix} 5 & 6 \\ 6 & 13 \end{bmatrix}$$

d) The linear estimator $\hat{V}(W)$ of V , given W is of the form $\hat{V}(W) = AW$

$$R_W = E[W W^T] = E[W^2] = \text{var}(W) + (E[W])^2 = 13 + 6^2 = 13 + 36 = 49$$

$$A^T = R_W^{-1} E[W V^T] = \frac{1}{49} \cdot 24$$

$$\hat{V}(W) = \frac{24}{49} W$$

e) The optimal (smallest MSE) affine estimator is of form

$$\hat{V}(W) = aW + b$$

$$a = \frac{\text{cov}(V, W)}{\text{var}(W)} = \frac{6}{13}$$

$$b = E[V] - E[W] \frac{\text{cov}(V, W)}{\text{var}(W)} = 3 - 6 \left(\frac{6}{13} \right) = 3 - \frac{36}{13} = \frac{39 - 36}{13} = \frac{3}{13}$$

$$\hat{V}(W) = \frac{6}{13} W + \frac{3}{13}$$

f) This is the optimal estimator because V and W are both Gaussian

g) $X - \bar{X}, Y - \bar{Y}, Z - \bar{Z}$ inputs to block box

Two outputs A and B

$$\begin{bmatrix} A \\ B \end{bmatrix} \quad \text{You want } \Sigma_{AB} = \begin{bmatrix} 3 & 2 \\ 2 & 5 \end{bmatrix}$$

This means you have $\text{var}(A) = 3$ and $\text{var}(B) = 5$ and $\text{cov}(A, B) = 2$.

$$\text{You have } \begin{aligned} A &= a_1 \overset{\circ}{X} + a_2 \overset{\circ}{Y} + a_3 \overset{\circ}{Z} & \text{where } \overset{\circ}{X} &= X - \bar{X} & N(0, 1) & E[\overset{\circ}{X}] = 0 \\ B &= b_1 \overset{\circ}{X} + b_2 \overset{\circ}{Y} + b_3 \overset{\circ}{Z} & \overset{\circ}{Y} &= Y - \bar{Y} & N(0, 1) & E[\overset{\circ}{Y}] = 0 \\ & & \overset{\circ}{Z} &= Z - \bar{Z} & N(0, 1) & E[\overset{\circ}{Z}] = 0 \end{aligned}$$

$$\text{cov}(A, B) = 2 = E[AB] - E[A]E[B] = a_1 b_1 E[\overset{\circ}{X}^2] + a_2 b_2 E[\overset{\circ}{Y}^2] + a_3 b_3 E[\overset{\circ}{Z}^2]$$

$$= a_1 b_1 + a_2 b_2 + a_3 b_3$$

$$\text{var}(A) = 3 = a_1^2 + a_2^2 + a_3^2$$

$$\text{var}(B) = 5 = b_1^2 + b_2^2 + b_3^2$$

An example thus is $a, b, = 2$

$$a_1 = 1, b_1 = 2$$

$$a_2 = \sqrt{2}, b_2 = 0$$

$$a_3 = 0, b_3 = 1$$

g cont...)

This would satisfy this

$$A = \overset{\circ}{X} + \sqrt{2}\overset{\circ}{Y}$$

$$B = 2\overset{\circ}{X} + \overset{\circ}{Z}$$

$$\text{cov}(A, B) = E[AB] - E[A]E[B] = E[2\overset{\circ}{X}^2] = 2E[\overset{\circ}{X}^2] = 2$$

$$\text{var}(A) = \text{var}(\overset{\circ}{X}) + 2\text{var}(\overset{\circ}{Y}) = 3$$

$$\text{var}(B) = 4\text{var}(\overset{\circ}{X}) + \text{var}(\overset{\circ}{Z}) = 5$$

$$h) \Lambda_{CD} = \begin{bmatrix} 2 & 0 \\ 0 & 7 \end{bmatrix}$$

This means that C and D are uncorrelated. Thus, using an affine estimator will not be useful at all. If the inputs are Gaussians and the outputs are Gaussians, the C and D are independent and output D gives you no information about output C.

$$4.19)_{a)} E[(X_t - X_s)^2] \geq 0$$

If $E X_t = E X_0$ for all t

$$E(X_t^2) = R_X(t, t) = R_X(0, 0) \text{ for all } t$$

$$E[(X_t - X_s)^2] \geq 0$$

$$E[X_t^2 - 2X_t X_s + X_s^2] \geq 0$$

$$E[X_t^2] - 2E[X_t X_s] + E[X_s^2] \geq 0$$

$$2R_X(0, 0) \geq 2E[X_t X_s]$$

$$E[X_t X_s] \leq R_X(0, 0)$$

$$R_X(t, s) \leq R_X(0, 0)$$

It is also true that

$$E[(X_t + X_s)^2] \geq 0$$

$$E[X_t^2 + 2X_t X_s + X_s^2] \geq 0$$

$$E[X_t^2] + 2E[X_t X_s] + E[X_s^2] \geq 0$$

$$2R_X(0, 0) \geq -2E[X_t X_s]$$

$$-R_X(t, s) \leq R_X(0, 0)$$

If $R_X(t, s) \leq R_X(0, 0)$ and $-R_X(t, s) \leq R_X(0, 0)$

then $|R_X(t, s)| \leq R_X(0, 0)$

$$K_X(t, s) = R_X(t, s) - E[X_t]E[X_s] = R_X(t, s) - (E X_0)^2$$

$$K_X(0, 0) = R_X(0, 0) - E[X_0]E[X_0] = R_X(0, 0) - (E X_0)^2$$

$$R_X(t, s) = K_X(t, s) + (E X_0)^2$$

$$R_X(0, 0) = K_X(0, 0) + (E X_0)^2$$

$$R_X(t, s) \leq R_X(0, 0)$$

$$K_X(t, s) + (E X_0)^2 \leq K_X(0, 0) + (E X_0)^2$$

$$K_X(t, s) \leq K_X(0, 0)$$

$$K_X(t, t) = R_X(t, t) - E[X_t]E[X_t] = R_X(0, 0) - E[X_0]E[X_0] = K_X(0, 0)$$

$$E[(X_t - EX_t) - (X_s - EX_s)]^2 \geq 0$$

$$E[(X_t - EX_t)^2 - 2(X_t - EX_t)(X_s - EX_s) + (X_s - EX_s)^2] \geq 0$$

$$K_X(t,t) - 2K_X(t,s) + K_X(s,s) \geq 0$$

$$2K_X(0,0) - 2K_X(t,s) \geq 0$$

$$K_X(t,s) \leq K_X(0,0)$$

$$E[(X_t - EX_t) + (X_s - EX_s)]^2 \geq 0$$

$$E[(X_t - EX_t)^2 + 2(X_t - EX_t)(X_s - EX_s) + (X_s - EX_s)^2] \geq 0$$

$$K_X(t,t) + 2K_X(t,s) + K_X(s,s) \geq 0$$

$$2K_X(0,0) + 2K_X(t,s) \geq 0$$

$$-K_X(t,s) \leq K_X(0,0)$$

If $K_X(t,s) \leq K_X(0,0)$ and $-K_X(t,s) \leq K_X(0,0)$ then

$$|K_X(t,s)| \leq K_X(0,0)$$

b) Autocorrelation and covariance functions are symmetric

$$R_X(t,s) = E[X_t X_s] = E[X_s X_t] = R_X(s,t)$$

$$K_X(t,s) = E[X_t X_s] - E[X_t]E[X_s] =$$

$$E[X_s X_t] - E[X_s]E[X_t] = K_X(s,t)$$

4.22) Θ uniform on $[-\pi, \pi]$

Y has mean m and variance σ^2

Θ and Y are independent

$$\{X(t); t \in \mathbb{R}\} \quad X(t) = Y \cos(2\pi f_0 t + \Theta)$$

Find mean and autocorrelation function.

$$E[X(t)] = E[Y \cos(2\pi f_0 t + \Theta)] = E[Y] E[\cos(2\pi f_0 t + \Theta)]$$

$$= 0$$

$$R_X(t, s) = E[X_t X_s]; \text{ all } t, s \in \mathbb{R}$$

$$= E[(Y \cos(2\pi f_0 t + \Theta))(Y \cos(2\pi f_0 s + \Theta))]$$

$$= E[Y^2] E[\cos(2\pi f_0 t + \Theta) \cos(2\pi f_0 s + \Theta)]$$

$$= (\sigma^2 + m^2) E[\cos(2\pi f_0 t + \Theta) \cos(2\pi f_0 s + \Theta)]$$

$$= (\sigma^2 + m^2) \int_{-\pi}^{\pi} \frac{1}{2\pi} \cos(2\pi f_0 t + \Theta) \cos(2\pi f_0 s + \Theta) d\Theta$$

$$= \frac{(\sigma^2 + m^2)}{2\pi} \int_{-\pi}^{\pi} [\cos(2\pi f_0 t) \cos(\Theta) - \sin(2\pi f_0 t) \sin(\Theta)] [\cos(2\pi f_0 s) \cos(\Theta) - \sin(2\pi f_0 s) \sin(\Theta)] d\Theta$$

$$= \frac{(\sigma^2 + m^2)}{2\pi} \int_{-\pi}^{\pi} [\cos(2\pi f_0 t) \cos(2\pi f_0 s) \cos^2(\Theta) - \sin(2\pi f_0 t) \cos(2\pi f_0 s) \sin(\Theta) \cos(\Theta) - \sin(2\pi f_0 s) \cos(2\pi f_0 t) \sin(\Theta) \cos(\Theta) + \sin(2\pi f_0 t) \sin(2\pi f_0 s) \sin^2(\Theta)] d\Theta$$

$$\left\{ \int_{-\pi}^{\pi} (\sin \Theta) (\cos \Theta) d\Theta = \frac{1}{2} \sin^2 \Theta \Big|_{-\pi}^{\pi} = 0 \right\}$$

$$= \frac{(\sigma^2 + m^2)}{2\pi} \int_{-\pi}^{\pi} [\cos(2\pi f_0 t) \cos(2\pi f_0 s) \cos^2 \Theta + \sin(2\pi f_0 t) \sin(2\pi f_0 s) \sin^2(\Theta)] d\Theta$$

$$= \frac{(\sigma^2 + m^2)}{2\pi} (\pi) [\cos(2\pi f_0 t) \cos(2\pi f_0 s) + \sin(2\pi f_0 t) \sin(2\pi f_0 s)]$$

$$\int_{-\pi}^{\pi} \cos^2 \Theta = \left[\frac{1}{2} \Theta + \frac{1}{4} \sin 2\Theta \right]_{-\pi}^{\pi} = \frac{2\pi}{2} = \pi$$

$$\int_{-\pi}^{\pi} \sin^2 \Theta = \left[\frac{1}{2} \Theta - \frac{1}{4} \sin 2\Theta \right]_{-\pi}^{\pi} = \frac{2\pi}{2} = \pi$$

$$= \frac{\sigma^2 + m^2}{2} [\cos(2\pi f_0 t - 2\pi f_0 s)]$$

$$= \frac{\sigma^2 + m^2}{2} \cos(2\pi f_0 (+-s))$$

$$\text{var}(Y) = E[Y^2] - (E[Y])^2$$

$$E[Y^2] = \sigma^2 + m^2$$

4.22 cont...)

$$\lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T x(t) dt = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T Y \cos(2\pi f_0 t + \theta) dt$$

$$= \lim_{T \rightarrow \infty} \frac{1}{T} \left[\frac{Y \sin(2\pi f_0 t + \theta)}{2\pi f_0} \right]_0^T$$

$$= \lim_{T \rightarrow \infty} \frac{1}{T} \left(\frac{Y}{2\pi f_0} \right) [\sin(2\pi f_0 T + \theta) - \sin(\theta)]$$

$$\left| \frac{Y}{2\pi f_0} [\sin(2\pi f_0 T + \theta) - \sin(\theta)] \right| \leq \left| \frac{2Y}{2\pi f_0} \right|$$

$$\left| \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T x(t) dt \right| \leq \lim_{T \rightarrow \infty} \frac{1}{T} \left| \frac{2Y}{2\pi f_0} \right| = 0 \quad \text{because } \left| \frac{2Y}{2\pi f_0} \right| \text{ is finite}$$

$$\therefore \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T x(t) dt = 0.$$

$$4.26) \hat{X}_n = a X_{n-1} + b$$

$$\epsilon \triangleq E[(X_n - \hat{X}_n)^2]$$

$$= E[X_n^2] - 2E[X_n \hat{X}_n] + E[\hat{X}_n^2]$$

$$= R_X(n, n) - 2aE[X_n X_{n-1}] - 2bE[X_n] + a^2 E[X_{n-1}^2] + 2abE[X_{n-1}] + b^2$$

$$= R_X(n, n) - 2aR_X(n, n-1) - 2bm_n + a^2 R_X(n-1, n-1) + 2abm_{n-1} + b^2$$

We want the derivative to be zero:

$$0 = \frac{d\epsilon}{db} = -2m_n + 2am_{n-1} + 2b$$

$$-m_n + am_{n-1} + b = 0$$

$$b = m_n - am_{n-1}$$

Notice $\epsilon = E[(X_n - aX_{n-1} - b)^2]$
 $= K_X(n, n) - 2aK_X(n-1, n-1) + a^2 K_X(n-1, n-1)$

$$\epsilon = R_X(n, n) - 2aR_X(n, n-1) - 2(m_n - am_{n-1})m_n + a^2 R_X(n-1, n-1) + 2a(m_n - am_{n-1})m_{n-1} + (m_n - am_{n-1})^2$$

$$= R_X(n, n) + a^2 R_X(n-1, n-1) - 2aR_X(n, n-1)$$

$$-2m_n^2 + 2am_n m_{n-1} + 2am_n m_{n-1} - 2a^2 m_{n-1}^2 + m_n^2 - 2am_n m_{n-1} + a^2 m_{n-1}^2$$

$$= K_X(n, n) + a^2 K_X(n-1, n-1) - 2aK_X(n, n-1)$$

$$0 = \frac{d\epsilon}{da} = -2K_X(n, n-1) + 2aK_X(n-1, n-1)$$

$$a = \frac{K_X(n, n-1)}{K_X(n-1, n-1)}$$

$$b = m_n - \frac{K_X(n, n-1)}{K_X(n-1, n-1)} m_{n-1}$$

$$4.26 \text{ cont.} \quad \hat{X}_n(X_{n-1}, X_{n-m}) = a_1 X_{n-1} + a_m X_{n-m} + b.$$

$$\epsilon \triangleq E[(X_n - \hat{X}_n)^2]$$

$$= E[X_n^2] - 2E[X_n \hat{X}_n] + E[\hat{X}_n^2]$$

$$= R_X(n, n) - 2E[X_n (a_1 X_{n-1} + a_m X_{n-m} + b)] + E[(a_1 X_{n-1} + a_m X_{n-m} + b)^2]$$

$$= R_X(n, n) - 2a_1 R_X(n, n-1) - 2a_m R_X(n, n-m) - 2b m_n$$

$$+ a_1^2 R_X(n-1, n-1) + a_m^2 R_X(n-m, n-m) + b^2$$

$$+ 2a_1 a_m R_X(n-1, n-m) + 2b(a_1 m_{n-1} + a_m m_{n-m})$$

$$0 = \frac{d\epsilon}{db} = -2m_n + 2b + 2(a_1 m_{n-1} + a_m m_{n-m})$$

$$0 = -m_n + b + a_1 m_{n-1} + a_m m_{n-m}$$

$$b = m_n - a_1 m_{n-1} - a_m m_{n-m}$$

$$\epsilon = R_X(n, n) - 2a_1 R_X(n, n-1) - 2a_m R_X(n, n-m) - 2(m_n - a_1 m_{n-1} - a_m m_{n-m}) m_n$$

$$+ a_1^2 R_X(n-1, n-1) + a_m^2 R_X(n-m, n-m) + (m_n - a_1 m_{n-1} - a_m m_{n-m})^2$$

$$+ 2a_1 a_m R_X(n-1, n-m) + 2(m_n - a_1 m_{n-1} - a_m m_{n-m})(a_1 m_{n-1} + a_m m_{n-m})$$

$$= K_X(n, n) - 2a_1 K_X(n, n-1) - 2a_m K_X(n, n-m) + a_1^2 K_X(n-1, n-1)$$

$$+ a_m^2 K_X(n-m, n-m) + 2a_1 a_m K_X(n-1, n-m)$$

$$0 = \frac{\partial \epsilon}{\partial a_1} = -2K_X(n, n-1) + 2a_1 K_X(n-1, n-1) + 2a_m K_X(n-1, n-m)$$

$$0 = \frac{\partial \epsilon}{\partial a_m} = -2K_X(n, n-m) + 2a_m K_X(n-m, n-m) + 2a_1 K_X(n-1, n-m)$$

$$K_X(n, n-1) = a_1 K_X(n-1, n-1) + a_m K_X(n-1, n-m)$$

$$K_X(n, n-m) = a_1 K_X(n-1, n-m) + a_m K_X(n-m, n-m)$$

$$a_m = \frac{K_X(n, n-m) - a_1 K_X(n-1, n-m)}{K_X(n-m, n-m)}$$

$$a_1 = \frac{K_X(n-1, n-m) K_X(n, n-m) - K_X(n, n-1) K_X(n-m, n-m)}{K_X(n-1, n-m)^2 - K_X(n-1, n-1) K_X(n-m, n-m)}$$

$$a_m = \frac{K_X(n-1, n-m) K_X(n, n-1) - K_X(n, n-m) K_X(n-1, n-1)}{K_X(n-1, n-m)^2 - K_X(n-1, n-1) K_X(n-m, n-m)}$$

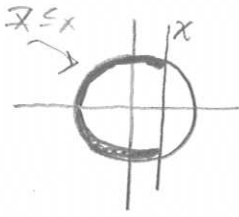
4.26 cont...)

$$\leftarrow a_m = 0 \text{ when } K_{\underline{x}}(n-1, n-m) K_{\underline{x}}(n, n-1) - K_{\underline{x}}(n, n-m) K_{\underline{x}}(n-1, n-1) = 0$$

This is true if the process is stationary or it's first-order Markov.

4.29)

$$a) F_{X(t)}(x) = \Pr(X(t) \leq x) = \Pr(\cos \theta \leq x)$$



$$\text{For } x < -1, F_{X(t)}(x) = 0$$

$$\text{For } x > 1, F_{X(t)}(x) = 1$$

$$F_{X(t)}(x) = \Pr(\theta \in [-\pi, -\cos^{-1}(x)] \cup [\cos^{-1}(x), \pi])$$

$$= 1 - \Pr(\theta \in (-\cos^{-1}(x), \cos^{-1}(x)))$$

$$= 1 - \int_{-\cos^{-1}(x)}^{\cos^{-1}(x)} \frac{d\theta}{2\pi}$$

$$= 1 - \frac{\cos^{-1}(x)}{\pi}$$

$$F_{X(t)}(x) = \begin{cases} 0, & x < -1 \\ 1 - \frac{\cos^{-1}(x)}{\pi}, & -1 \leq x \leq 1 \\ 1, & x > 1 \end{cases}$$

$$b) E X(t) = E[\cos(t + \theta)] = \int_{-\pi}^{\pi} \cos(t + \theta) d\theta \frac{1}{2\pi} = \underline{0}$$

$$c) K_X(t, s) = E[X(t)X(s)] = E[\cos(t + \theta) \cos(s + \theta)]$$

$$= \int_{-\pi}^{\pi} \cos(t + \theta) \cos(s + \theta) \frac{d\theta}{2\pi}$$

$$= \int_{-\pi}^{\pi} \left(\frac{1}{2} \cos(t + s + 2\theta) + \frac{1}{2} \cos(t + s) \right) \frac{d\theta}{2\pi}$$

$$= \underline{\frac{1}{2} \cos(t + s)}$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} [\cos(t) \cos \theta - \sin(t) \sin \theta] [\cos(s) \cos \theta - \sin(s) \sin \theta]$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} \cos(s) \cos(t) \cos^2 \theta - \sin(t) \cos(s) \sin \theta \cos \theta - \sin(s) \cos(t) \sin \theta \cos \theta + \sin(s) \sin(t) \sin^2 \theta$$

$$= \frac{1}{2\pi} (\pi (\cos(s) \cos(t) - \sin(s) \sin(t))) = \frac{1}{2} \cos(s - t)$$

$$4.30) a) E[Y_n] = E[X_n + W_n] = EX_n + EW_n = m$$

$$\begin{aligned} R_Y(n, k) &= E[(X_n + W_n)(X_k + W_k)] \\ &= E[X_n X_k] + \cancel{E[X_n W_k]}^0 + \cancel{E[W_n X_k]}^0 + E[W_n W_k] \\ &= R_X(n, k) + R_W(n, k) \\ &= R_X(n, k) + \sigma_w^2 \delta_{n-k} \end{aligned}$$

$$\begin{aligned} K_Y(n, k) &= R_Y(n, k) - E\bar{Y}_n E\bar{Y}_k = R_X(n, k) + \sigma_w^2 \delta_{n-k} - m^2 \\ &= K_X(n, k) + \sigma_w^2 \delta_{n-k} \end{aligned}$$

$$\begin{aligned} b) R_{XY}(k, j) &= E[X_k Y_j] \\ &= E[X_k (X_j + W_j)] \\ &= E[X_k X_j] + E[X_k W_j] \\ &= R_X(k, j) \end{aligned}$$

c) This is the same as Problem 4.26

$$\hat{X}_n = a Y_n + b$$

↑
 X_{n-1} in 4.26

$$a = \frac{K_X(n, n-1)}{K_X(n-1, n-1)} \stackrel{4.30f}{=} \frac{E[X_n X_{n-1}] - E[X_n]E[X_{n-1}]}{\sum_{4.26} E[Y_n Y_{n-1}] - E[Y_n]E[Y_{n-1}]} = \frac{E[X_n Y_n]}{E[Y_n^2]} = \boxed{\frac{R_X(n, n)}{R_X(n, n) + \sigma_w^2}}$$

$$b = \underbrace{m_n - \frac{K_X(n, n-1)}{K_X(n-1, n-1)}}_{4.26} \stackrel{m_{X_{n-1}}}{m_{n-1}} = m_{X_n} - \frac{R_X(n, n)}{R_X(n, n) + \sigma_w^2} m_{Y_n} = \boxed{m - \frac{R_X(n, n)}{R_X(n, n) + \sigma_w^2} m}$$

4.30d) Using 4.26

$$4.26: \hat{\bar{X}}_n(\bar{X}_{n-1}, \bar{X}_{n-m}) = a_1 \bar{X}_{n-1} + a_m \bar{X}_{n-m} + b$$

$$4.30: \hat{\bar{Y}}_n(\bar{Y}_n, \bar{Y}_{n-1}) = a_1 \bar{Y}_n + a_2 \bar{Y}_{n-1} + b$$

$$4.26: q_1 = \frac{K_{\bar{X}}(n-1, n-m) K_{\bar{X}}(n, n-m) - K_{\bar{X}}(n, n-1) K_{\bar{X}}(n-m, n-m)}{K_{\bar{X}}(n-1, n-m)^2 - K_{\bar{X}}(n-1, n-1) K_{\bar{X}}(n-m, n-m)}$$

$$4.30: q_1 = \frac{K_{\bar{Y}}(n, n-1) K_{\bar{X}\bar{Y}}(n, n-1) - K_{\bar{X}\bar{Y}}(n, n) K_{\bar{Y}}(n-1, n-1)}{K_{\bar{Y}}(n, n-1)^2 - K_{\bar{Y}}(n, n) K_{\bar{Y}}(n-1, n-1)} = \frac{(R_{\bar{X}}(n, n-1) - m^2) R_{\bar{X}}(n, n-1) - R_{\bar{X}}(n, n) [R_{\bar{Y}}(n, n) + \delta_w^2]}{(R_{\bar{Y}}(n, n-1) - m^2)^2 - (R_{\bar{Y}}(n, n) + \delta_w^2) (R_{\bar{Y}}(n-1, n-1) + \delta_w^2)}$$

$$4.26: q_m = \frac{K_{\bar{X}}(n-1, n-m) K_{\bar{X}}(n, n-1) - K_{\bar{X}}(n, n-m) K_{\bar{X}}(n-1, n-1)}{K_{\bar{X}}(n-1, n-m)^2 - K_{\bar{X}}(n-1, n-1) K_{\bar{X}}(n-m, n-m)}$$

$$4.30: a_2 = \frac{K_{\bar{Y}}(n, n-1) K_{\bar{X}\bar{Y}}(n, n) - K_{\bar{X}\bar{Y}}(n, n-1) K_{\bar{Y}}(n, n)}{K_{\bar{Y}}(n, n-1)^2 - K_{\bar{Y}}(n, n) K_{\bar{Y}}(n-1, n-1)} = \frac{(R_{\bar{X}}(n, n-1) - m^2) R_{\bar{X}}(n, n) - R_{\bar{X}}(n, n-1) [R_{\bar{Y}}(n, n) + \delta_w^2]}{(R_{\bar{Y}}(n, n-1) - m^2)^2 - (R_{\bar{Y}}(n, n) + \delta_w^2) (R_{\bar{Y}}(n-1, n-1) + \delta_w^2)}$$

$$4.26: b = m_n - a_1 m_{n-1} - a_m m_{n-m}$$

$$4.30: b = m_{\bar{X}_n} - a_1 m_{\bar{Y}_n} - a_2 m_{\bar{Y}_{n-1}}$$

$$b = m(1 - q_1 - a_2)$$

4.31)

$$Y_1 = W_1$$

$$Y_2 = W_2$$

$$Y_3 = W_1 \oplus W_2$$

$$P_{Y_1}(x) = P_{Y_2}(x) = P_{Y_3}(x) = \frac{1}{2}; x = 0, 1$$

$$P_{X_i}(x) = \frac{1}{2}; x = 0, 1, \text{ identically distributed}$$

$P_{X_i, X_j}(a, b)$ has one of the following three forms, P_{Y_1, Y_2} , P_{Y_1, Y_3} , P_{Y_2, Y_3}

$$P_{Y_1, Y_2} = P_{Y_1} P_{Y_2} \text{ because } W_1 \text{ and } W_2 \text{ are independent.}$$

$$\begin{aligned} P_{Y_1, Y_3}(a, b) &= \Pr(W_1(n) = a, W_1(n) \oplus W_2(n) = b) \\ &= \underbrace{\Pr(W_1(n) \oplus W_2(n) = b \mid W_1(n) = a)}_{\Pr(W_2(n) = a \oplus b) = 1/2} \underbrace{\Pr(W_1(n) = a)}_{1/2} \\ &= \frac{1}{4} \quad \forall a, b \end{aligned}$$

$$P_{Y_2, Y_3} = P_{Y_2} P_{Y_3}$$

The process is not iid. If X_0 and X_1 are known, then $X_2 = X_0 \oplus X_1$.

$$P_{X_0, X_1, X_2} \neq \prod_{i=0}^2 P_{X_i}$$