

Response of First Order Transfer Functions

$$X(s) \longrightarrow G(s) = \frac{K}{\tau s + 1} \longrightarrow Y(s)$$

First Order Functions

- Time Domain

$$\tau \frac{dy}{dt} + y = Kx$$

- Laplace Domain

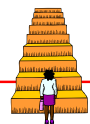
$$\frac{Y(s)}{X(s)} = G(s) = \frac{K}{\tau s + 1}$$

Input Functions (i.e., X(s))

Step	$u(s) = \frac{M}{s}$	(5-6)
Ramp	$u(s) = \frac{a}{s^2}$	(5-8)
Rectangular pulse	$u(s) = \frac{h}{s} (1 - e^{-t_w s})$	(5-11)
Triangular pulse	$u(s) = \frac{2}{t_w} \left(\frac{1 - 2e^{-t_w s/2} + e^{-t_w s}}{s^2} \right)$	(5-13)
Sine wave	$u(s) = \frac{A\omega}{s^2 + \omega^2}$	(5-15)
Impulse	$u(s) = a$	p. 76

(slope = $t_w/2$)

Response to Step



$$Y(s) = X(s)G(s)$$

$$X(s) = \frac{M}{s}$$

$$G(s) = \frac{K}{\tau s + 1}$$

$$Y(s) = \frac{KM}{s(\tau s + 1)}$$

$$y(t) = KM(1 - e^{-t/\tau})$$

(5-18)

Response to Ramp



$$Y(s) = X(s)G(s)$$

$$X(s) = \frac{a}{s^2}$$

$$G(s) = \frac{K}{\tau s + 1}$$

$$Y(s) = \frac{Ka}{s^2(\tau s + 1)}$$

$$y(t) = Ka\tau(e^{-t/\tau} - 1) + Kat$$

(5-22)

Response to Sine Wave



$$Y(s) = X(s)G(s)$$

$$X(s) = \frac{A\omega}{s^2 + \omega^2}$$

$$G(s) = \frac{K}{\tau s + 1}$$

$$Y(s) = \frac{KA\omega}{(s^2 + \omega^2)(\tau s + 1)} = KA\omega \left[\frac{a}{\tau s + 1} + \frac{bs + c}{s^2 + \omega^2} \right]$$

$$y(t) = \frac{Ka}{\omega^2 \tau^2 + 1} (\omega \tau e^{-t/\tau} - \omega \tau \cos \omega t + \sin \omega t)$$

(5-25)

Time Delays (θ)

In time domain:

- Replace t with $(t-\theta)$ and multiply by $S(t-\theta)$

$$f(t-\theta) \cdot S(t-\theta)$$

In Laplace domain

- Multiply by $e^{-\theta s}$

$$e^{-\theta s} F(s)$$

Example: FOPDT

- This is a response of a first order model to a step function M

- First order with a step function is:

$$y(t) = KM(1 - e^{-t/\tau}) \quad Y(s) = \frac{KM}{s(\tau s + 1)}$$

- Now add time delay

$$y(t) = KM(1 - e^{-(t-\theta)/\tau}) \cdot S(t-\theta)$$

$$Y(s) = \frac{KM \cdot e^{-\theta s}}{s(\tau s + 1)}$$

Integrating Process

- Pumped Tank

$$A \frac{dh}{dt} = q_i - q$$

$$sAH'(s) = Q_i'(s) - Q'(s)$$

$$H'(s) = \frac{1}{sA} [Q_i'(s) - Q'(s)]$$

$$\frac{H'(s)}{Q_i'(s)} = \frac{1}{sA}$$

$$\frac{H'(s)}{Q'(s)} = -\frac{1}{sA}$$

- This is not a first order model
- Called an integrating process (no steady-state gain)
- Step function in q or q_i results in ramp in h !!

$$Q_i'(s) = \frac{M}{s}$$

$$H'(s) = \frac{M}{s^2 A}$$

Pumped Tank Example

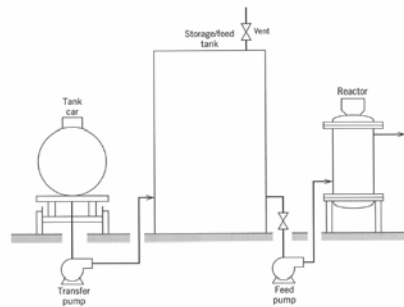


Figure 5.6 Unloading and storage facility for a continuous reactor.

Problem 4.7

H , L , and V are molar flow rates
 y 's and x 's are mole fractions in vapor and liquid

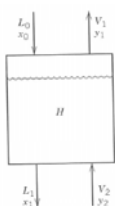


Figure E4.7

Stirred tank blending system
 (or stage on distillation column)

- Wanted:

$$\frac{X_1'(s)}{X_0'(s)} \quad \frac{X_1'(s)}{Y_2'(s)} \quad \frac{Y_1'(s)}{X_0'(s)} \quad \frac{Y_1'(s)}{Y_2'(s)}$$

- Given:

$$\frac{dH}{dt} = L_0 + V_2 - (L_1 + V_1)$$

$$\frac{dx_1 H}{dt} = x_0 L_0 + y_2 V_2 - (x_1 L_1 + y_1 V_1)$$

$$y_1 = a_0 + a_1 x_1 + a_2 x_1^2 + a_3 x_1^3$$

Vapor pressure correlation

Assumptions

- Molar holdup H is constant $\Rightarrow \frac{dH}{dt} = 0$
- Constant molar overflow $\Rightarrow \begin{matrix} L_0 = L_1 \\ V_1 = V_2 \end{matrix}$
- Simplification: only use L and V (no subscripts)