

# Chemical Engineering 436

## Exam #3 Review

<b>Chapter 8</b>	PID controller transfer functions Ideal derivative vs. practical Reverse acting vs. direct acting Trends
<b>Chapter 9 Equipment</b>	Valves ( <i>We covered this early in the semester</i> ) <ul style="list-style-type: none"><li>- how to linearize and get <math>G_v</math></li><li>- Air to Open vs Air to Close</li></ul> Gains from transmitters, measurement devices
<b>Skipped Chapter 10</b>	( <i>Safety, Fault Tree, Risk Assessment</i> ) – covered in ChEn 311
<b>Chapter 11 Block Diagrams</b>	Get block diagram from physical diagram Closed loop transfer functions Block diagram algebra Closed loop behavior <ul style="list-style-type: none"><li>- time constants</li><li>- final values as <math>t</math> approaches <math>\infty</math> (<math>Y/Y_{sp}=?</math>, <math>Y/D=?</math>)</li><li>- offset (P-control only)</li></ul>
<b>Stability</b>	Definition of stability Characteristic equation Methods <ul style="list-style-type: none"><li>- Roots of Polynomial (Charact. Eqn.)</li><li>- Routh<ul style="list-style-type: none"><li>- Padé approximation for time delay<math display="block">e^{-\theta s} = \frac{1 - \frac{\theta}{2}s}{1 + \frac{\theta}{2}\theta s}</math></li></ul></li><li>- Direct substitution<ul style="list-style-type: none"><li>- Euler identity for time delay (<math>e^{-j\omega\theta} = \cos(\omega\theta) - j \sin(\omega\theta)</math>)</li></ul></li><li>- Root locus</li></ul>
<b>Chapter 12 Controller Design</b>	<i>Direct Synthesis &amp; IMC (add model to correct control)</i> <i>PID parameters from ITAE and IMC</i> <i>Tuning Relations (like in Control Station)</i>

*Note: Chapter 12 was not formally covered, but it has good material.*