

Lecture 12 - Simplifying Transport Equations

I. Basis for simplifications

* Implicit in our discussion in lecture 10 (on solving 1D equations) was the fact that our equations did indeed simplify to 1D. Today we are going to revisit that idea.

* We are going to be a bit more careful, and we are going to rely on ideas from the last lecture on scaling to do this.

* Our book lists four different reasons for getting rid of terms in a transport equation:

1. Symmetry

2. Differing length scales

3. Differing resistance scales

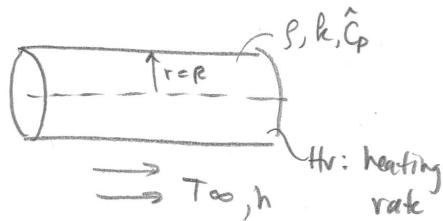
4. Differing time scales.

} Note these three have to do with different scales.

Need "scaling analysis"

* It is easier to talk about these four reasons in terms of an example, rather than abstractedly. Let's return to our heated-wire example.

* Example: Heated wire



$$\frac{dT}{dr} \Big|_{r=0} = 0$$

$$\frac{dT}{dr} \Big|_{r=R} = -\frac{h}{k} [T(R) - T_\infty]$$

$$\hat{C}_p \frac{dT}{dt} = k \nabla^2 T + hV$$

$$\hat{C_P} \left[\frac{\partial T}{\partial t} + v_r \frac{\partial T}{\partial r} + \frac{v_\theta}{r} \frac{\partial T}{\partial \theta} + v_z \frac{\partial T}{\partial z} \right] = k \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 T}{\partial \theta^2} + \frac{\partial^2 T}{\partial z^2} \right] + H_V$$

- First, recall that the wire is solid, so $v_r = v_\theta = v_z = 0$

1. Symmetry

- we know that the problem is cylindrically symmetric. That means $T(r, \theta, z) = T(r, \theta', z)$ or $\frac{\partial T}{\partial \theta} = 0$.
- Symmetry is the main reason for having using curvilinear coordinates. (Remember, I said this when we learned about them in lec 2.)
- Because our PDE is non-linear, there may be multiple solutions: some that are symmetric and some that aren't. For example: laminar & turbulent pipe flow.

2. Differing length scales

- If one length scale is much smaller, or larger, than the others, that can lead to simplifications.
- Consider an OOM analysis of the steady version of the energy equation above:

$$0 = \underbrace{\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right)}_{\sim \frac{\Delta T}{R^2}} + \underbrace{\frac{\partial^2 T}{\partial z^2}}_{\sim \frac{\Delta T}{L^2}}$$

T_c : center temp.
 $\Delta T \approx T_c - T_\infty$

- let $\theta = \frac{T - T_\infty}{\Delta T}$, $\tilde{r} = r/R$, $\tilde{z} = z/L$

- non dimensionalize:

$$0 = \frac{1}{\tilde{r} R} \frac{\partial}{\partial (\tilde{r} R)} \left[\tilde{r} R \frac{\partial (\theta \Delta T)}{\partial (\tilde{r} R)} \right] + \frac{\partial^2 (\theta \Delta T)}{\partial (\tilde{z} L)^2}$$

$$\Theta = \frac{\Delta T}{R^2} \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \Theta}{\partial r} \right) + \frac{\Delta T}{L^2} \frac{\partial^2 \Theta}{\partial z^2} \right)$$

$$\Theta = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \Theta}{\partial r} \right) + \frac{R^2}{L^2} \frac{\partial^2 \Theta}{\partial z^2}$$

- when $R \ll L$, the temperature gradient along the z -direction is small. we can then neglect it!

- There are "edge effects" in the z -dir if we get to the end of the wire where $L \approx R$.

3. Differing resistance scales

- Remember, last time we non-dimensionalized our 1D problem

$$\frac{k}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) = -h_v \quad \frac{\partial T}{\partial r} \Big|_{r=0} = 0, \quad \frac{\partial T}{\partial r} \Big|_{r=R} = -\frac{h}{k} [T(R) - T_\infty]$$

$$\Theta = \frac{T - T_\infty}{T_s - T_c}, \quad \eta = r/R$$

$$\frac{1}{\eta} \frac{\partial}{\partial \eta} \left(\eta \frac{\partial \Theta}{\partial \eta} \right) = 1 \quad \frac{\partial \Theta}{\partial \eta} \Big|_{\eta=0} = 0 \quad \frac{\partial \Theta}{\partial \eta} \Big|_{\eta=1} = -Bi \Theta(1)$$

$$Bi = hR/k$$

- The Biot # is a ratio of resistances.

resistance to heat transfer in the fluid : $1/hR$

resistance " " " " solid : $1/k$

(a resistance in my definition here is $\frac{1}{\text{conductivity}}$)

$$Bi = \frac{\text{solid resistance}}{\text{fluid resistance}} = \frac{1/k}{1/hR} = \frac{hR}{k}$$

- When $Bi \ll 1$, the resistance in the solid is small.

Now:

$$\frac{\partial \Theta}{\partial \eta} \Big|_{\eta=1} \approx 0$$

- This makes the solution to θ be a constant!

$$\theta = \frac{\eta^2}{4} + C_1 \ln \eta + C_2 \quad (\text{from Eq. 10})$$

$$\frac{d\theta}{d\eta} = \frac{\eta}{2} + \frac{C_1}{\eta} = 0 \quad \text{for } \eta=0 \text{ & } \eta=1$$

$\theta = C_2$ only!

- We have "lost" another dimension! Now, we have a "0D" problem. This is called a lumped model.

You can find the constant using a macroscopic balance.
(more on this in a minute)

4. Differing time scales

- Let's suppose we didn't drop the time derivative:

$$\rho \hat{C}_P \frac{\partial T}{\partial t} = \frac{k}{R} \frac{1}{r} \left(r \frac{\partial T}{\partial r} \right) + H_V$$

- The diffusion problem has an inherent timescale called the diffusion time (neglecting H_V for a moment)

$$\frac{\partial T}{\partial t} = \frac{\alpha}{r} \frac{1}{r} \left(r \frac{\partial T}{\partial r} \right) \quad \text{let } \theta = \frac{T - T_{\infty}}{\Delta T}, \tilde{r} = r/k, \tilde{t} = t/t_d$$

$$\frac{\Delta T}{t_d} \frac{\partial \theta}{\partial \tilde{t}} = \frac{\alpha \Delta T}{R^2} \frac{1}{\tilde{r}} \frac{1}{\tilde{r}} \left(\tilde{r} \frac{\partial \tilde{T}}{\partial \tilde{r}} \right)$$

$$\frac{\Delta T}{t_d} \sim \frac{\alpha \Delta T}{R^2} \Rightarrow \boxed{t_d \sim \frac{R^2}{\alpha}} \quad [\equiv] \frac{\text{len}^2}{\text{len}^2/\text{time}} [\equiv] \text{time}$$

↑
diffusion time

- Now, suppose that H_V changes with some other time scale, t_p . This "process time" is set by external considerations (change in wire current).

- setting $\tilde{t} = t/t_p$ gives instead

$$\frac{\Delta T}{t_p} \frac{\partial \theta}{\partial \tilde{t}} = \frac{\Delta T}{t_d} \frac{1}{\tilde{r}} \frac{1}{\tilde{r}} \left(\tilde{r} \frac{\partial \tilde{T}}{\partial \tilde{r}} \right) + \frac{H_V(t)}{\rho \hat{C}_P} \quad \begin{matrix} \leftarrow \\ \text{now a function of time.} \end{matrix}$$

$$\frac{t_d}{t_p} \frac{\partial \theta}{\partial t} = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) + \frac{t_d H_v}{p \bar{c}_p}$$

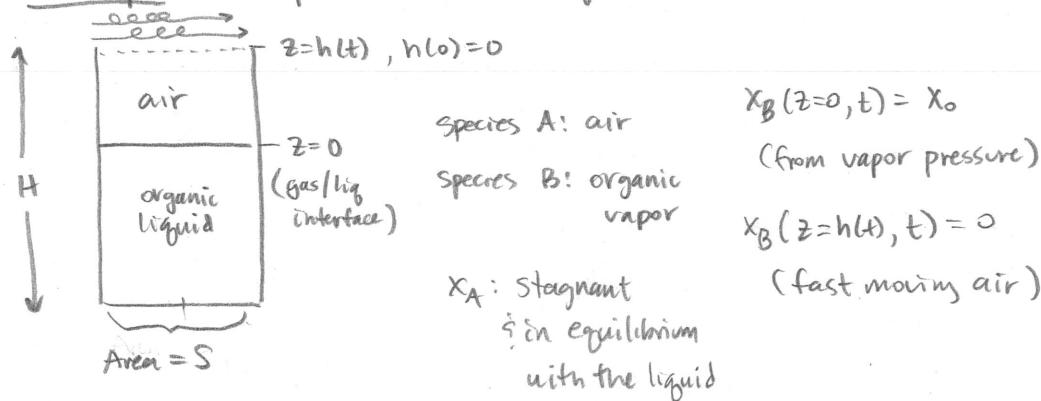
- There are three possibilities:

- (i) $t_d \ll t_p$: Diffusion is fast. This leads to a steady-state or pseudo steady-state problem.
- (ii) $t_d \gg t_p$: Diffusion is slow. We will look at this in chapter 4. (similarity)
- (iii) $t_d \sim t_p$: We have to solve the whole PDE, see ch. 5.

II. Pseudo-steady state problems.

- * What happens if (like in the last example) we have some process with a slow timescale, but we still need to account for it?
 - We can solve the 1D transport Eq. as if it is steady
 - We can use this to tell us information about the process time, if it is related. Usually this involves a macroscopic balance.

- * Example: Evaporation of a liquid column.



- * What is $h(t)$? Do a macroscopic balance on the liquid

$$\frac{d}{dt} \int_{V(t)} c_B dV = \int_{S(t)} N_B|_{\text{liquid}} \cdot n dS$$

- Let $c_{B,L} = \frac{1}{V} \int c_B dV$, the average concentration

- Assume $N_{B,z}$ is not a function of r .

$$\frac{d}{dt}(c_{B,L} V) = N_{B,z} |_{\text{liquid}} \cdot S$$

$$V = S \cdot h(t)$$

$c_{B,L} = \text{constant}$.

(if V is big, it shouldn't change very much.)

$$\frac{dh}{dt} = \frac{N_{B,z} |_{\text{liquid}}}{c_{B,L}}$$

- How get $N_{B,z} |_{\text{liquid}}$? Use interface balance:

$$(F - v_I) |_{\text{liq}} = (F - v_I) |_{\text{gas}}$$

$$N_{B,z} |_{\text{liq}} = N_{B,z} |_{\text{gas}}$$

* Moving reference frame of the interface. v_I is the same.

- What is the scale for t_p ?

$$\frac{dh}{dt} = \frac{N_{B,z} |_{\text{gas}}}{c_{B,L}} \Rightarrow \frac{H}{t_p} \sim \underbrace{\frac{DAB}{c_{B,L}}}_{\text{NB}} \frac{C_{B,G}/H}{C_{B,G}}$$

$$t_p \sim \frac{H^2 c_{B,L}}{DAB C_{B,G}}$$

$$t_d \sim \frac{H^2}{DAB}$$

* if $c_{B,L} \gg c_{B,G}$ then we are pseudo steady.

* We can solve the species mass diffusion equation to

find $c_B(z)$ and $N_{B,z}$. Use same methods as before. I'm out of time, but I'll post the notes as a supplement.