

Chemical Engineering 378

Science of Materials Engineering

Lecture 36

Magnetic Properties



Spiritual Thought

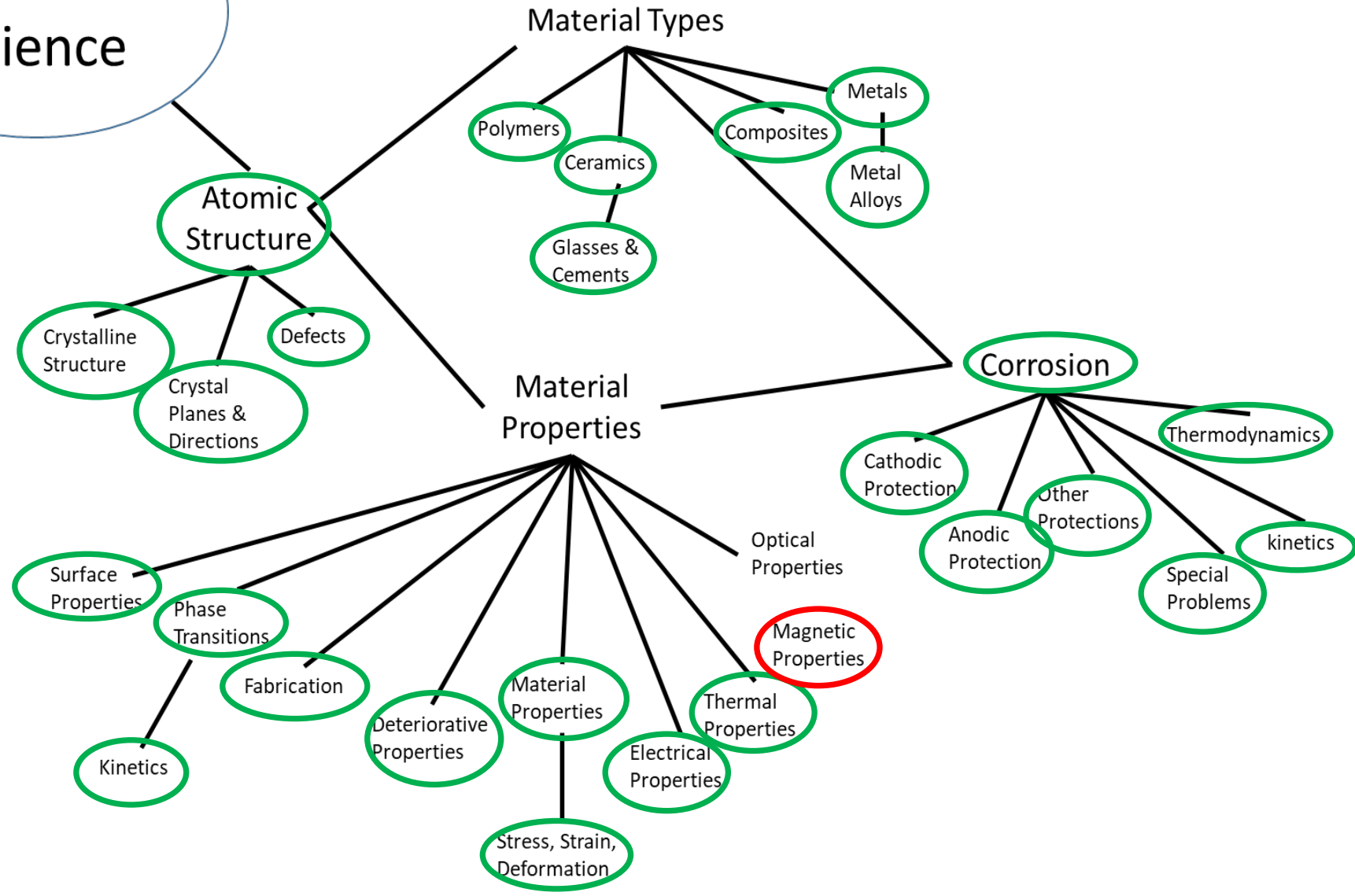
“I urge you to stretch beyond your current spiritual ability to receive personal revelation, for the Lord has promised that ‘if thou shalt [seek], thou shalt receive revelation upon revelation, knowledge upon knowledge, that thou mayest know the mysteries and peaceable things—that which bringeth joy, that which bringeth life eternal.’”

- President Russel M. Nelson



Materials Roadmap

Materials Science



OEP Help

Cylinder Hoop Stress Formula

$$\sigma_H = \frac{Pd}{2t}$$

σ_H – cylinder hoop stress in Pa

P – internal pressure in Pa

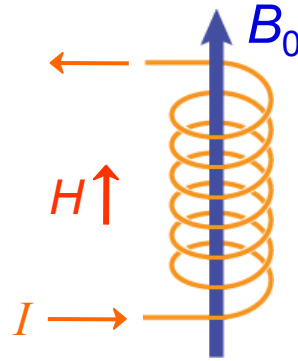
d – cylinder inside diameter in m

t – wall thickness in m



Generation of a Magnetic Field - Vacuum

- Created by current through a coil:



N = total number of turns

ℓ = length of each turn (m)

I = current (ampere)

H = applied magnetic field (ampere-turns/m)

B_0 = magnetic flux density in a vacuum (tesla)

- Computation of the applied magnetic field, H :

$$H = \frac{NI}{\ell}$$

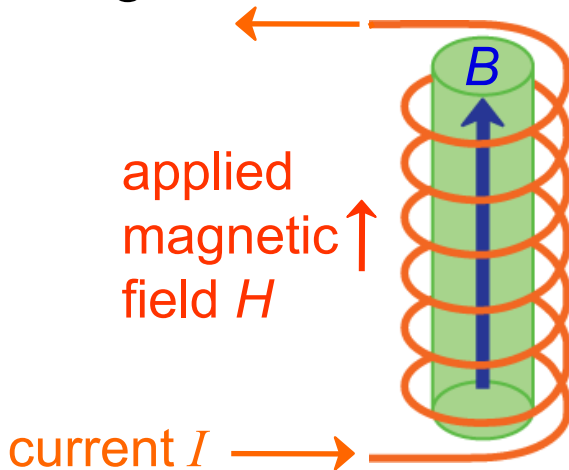
- Computation of the magnetic flux density in a vacuum, B_0 :

$$B_0 = \mu_0 H$$

permeability of a vacuum
(1.257×10^{-6} Henry/m)

Generation of a Magnetic Field -- within a Solid Material

- A magnetic field is induced in the material



B = Magnetic Induction (tesla)
inside the material

$$B = \mu H$$

permeability of a solid

- Relative permeability (dimensionless) $\mu_r = \frac{\mu}{\mu_0}$

Generation of a Magnetic Field - within a Solid Material (cont.)

- Magnetization

$$M = \chi_m H$$

Magnetic susceptibility
(dimensionless)

- B in terms of H and M

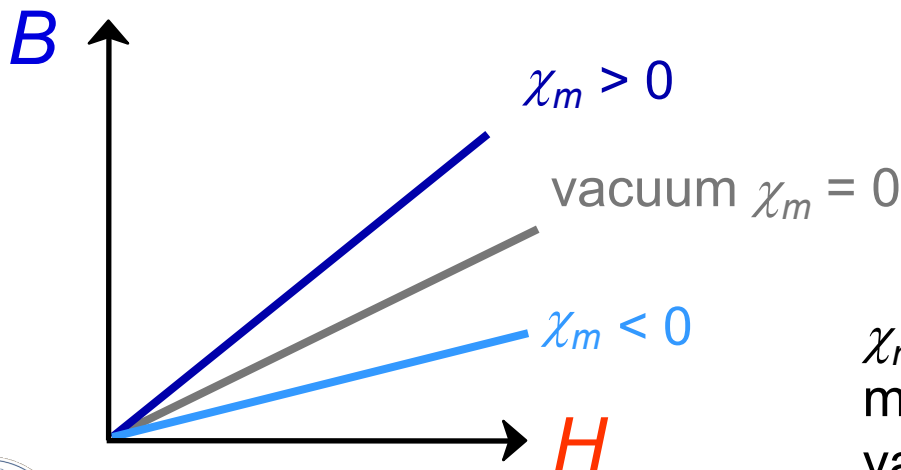
$$B = \mu_0 H + \mu_0 M$$

- Combining the above two equations:

$$B = \mu_0 H + \mu_0 \chi_m H$$

$$= (1 + \chi_m) \mu_0 H$$

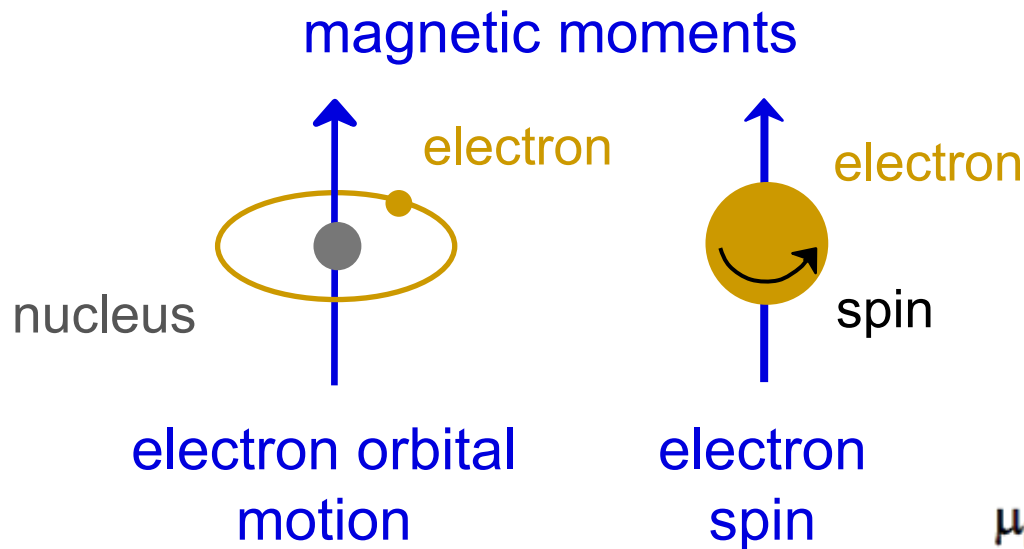
permeability of a vacuum:
(1.26×10^{-6} Henry/m)



χ_m is a measure of a material's magnetic response relative to a vacuum

Origins of Magnetic Moments

- Magnetic moments arise from electron motions and the spins on electrons.



Adapted from Fig. 20.4,
Callister & Rethwisch 10e.

Bohr Magnetons

$$\mu_B = 9.27 \times 10^{-24} \text{ Am}^2$$

- Net atomic magnetic moment:
-- sum of moments from all electrons.

Iron Has 2.22 Bohr
Magnetons, so:

$$M_s = 2.22 \mu_B N$$

$$B_s = \mu_0 M_s$$

- Four types of response...

Example 1

Given that the net magnetic moment per atom of iron is 2.22 Bohr magnetons, what are the saturation magnetization (M_s) and saturation flux density (B_s) for iron?

$$M_s = 2.22 \mu_B N$$

$$B_s = \mu_o M_s$$

where M_s = the saturation magnetization

$$\mu_o = 1.257 \times 10^{-6} \text{ Henry/m}$$

$$\mu_B = 9.27 \times 10^{-24} \text{ Am}^2$$

$$N = \text{number of atoms/m}^3$$



Example 1 Solution

First find N (atoms/m³)

$$N = \frac{\rho N_A}{A_{Fe}}$$

$$N = \frac{\left(7.97 \frac{g}{cm^3}\right) (6.022 \times 10^{23} \frac{atoms}{mol})}{\left(\frac{m}{100 cm}\right)^3 (55.85 \frac{g}{mol})}$$

$$N = 8.6 \times 10^{28} \frac{atoms}{m^3}$$



Example 1 Solution

$$\mathbf{M_s = 2.22 \mu_B N}$$

$$M_s = \left(\frac{2.22 \text{ Bohr magneton}}{\text{atom}} \right) \left(\frac{9.27 \times 10^{-24} \text{ A m}^2}{\text{Bohr magneton}} \right) \left(\frac{8.6 \times 10^{28} \text{ atoms}}{\text{m}^3} \right)$$

$$M_s = 1.77 \times 10^6 \frac{\text{A}}{\text{m}}$$

$$\mathbf{B_s = \mu_o M_s}$$

$$B_s = 1.257 \times 10^{-6} \frac{\text{H}}{\text{m}} (1.77 \times 10^6 \frac{\text{A}}{\text{m}})$$

$$B_s = 2.22 \text{ Tesla}$$



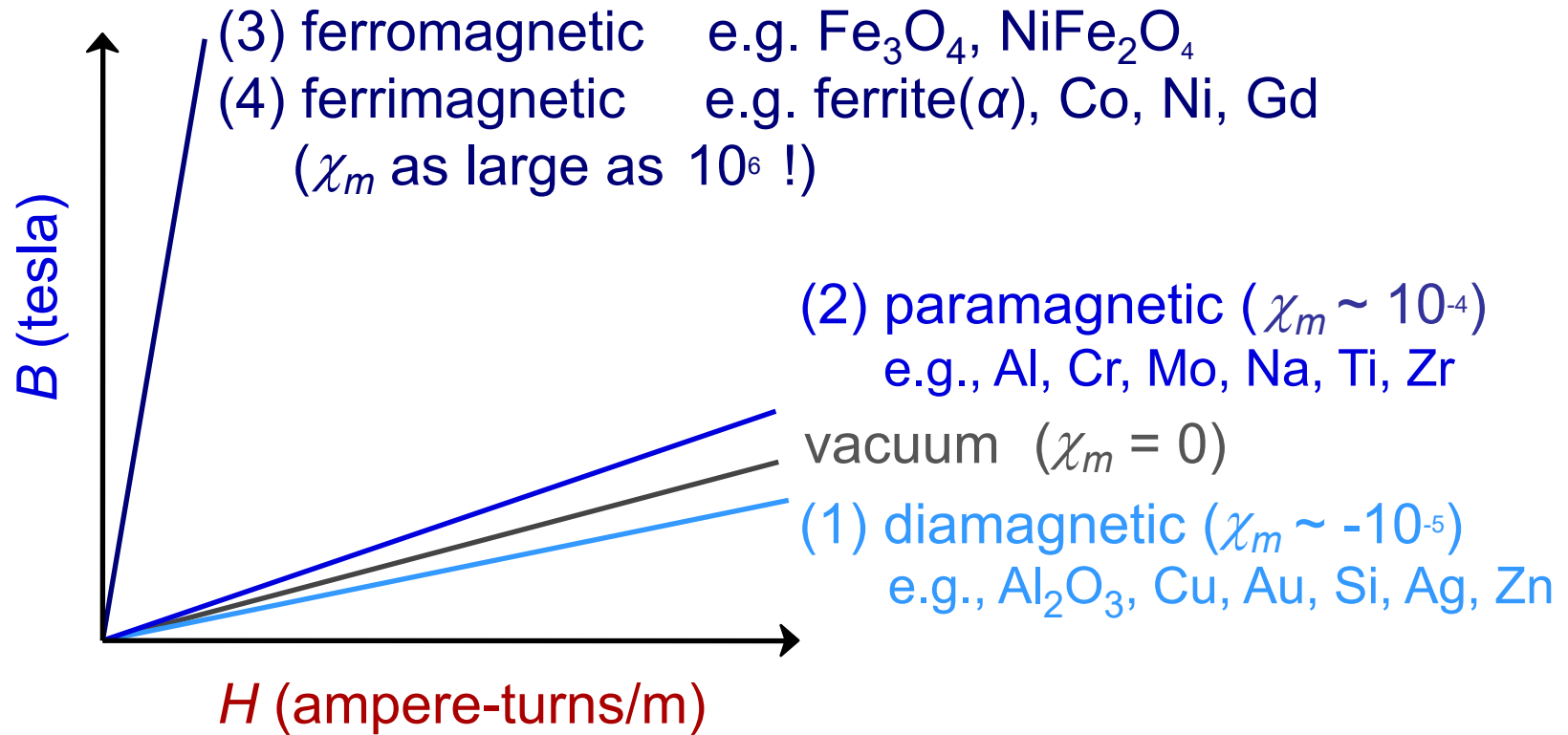
Unit Conversions

- Units of the Henry are Webers per Ampere
- Units of the Weber are Volt-seconds
- Tesla is a Wb/m^2

$$\text{Tesla} = \frac{\text{H}}{\text{m}} \frac{\text{A}}{\text{m}} = \frac{\text{Wb}}{\text{A m}} \frac{\text{A}}{\text{m}} = \frac{\text{Wb}}{\text{m}^2}$$

$$\begin{aligned} \text{Tesla} &= \frac{\text{Wb}}{\text{m}^2} \frac{\text{Vs}}{\text{Wb}} = \frac{\text{Vs}}{\text{m}^2} = \frac{\text{Js}}{\text{C m}^2} = \frac{\text{J}}{\text{A m}^2} \\ &= \frac{\text{Nm}}{\text{A m}^2} = \frac{\text{N}}{\text{A m}} = \frac{\text{kgm}}{\text{s}^2 \text{A m}} = \frac{\text{kgms}}{\text{s}^2 \text{C m}} = \frac{\text{kg}}{\text{Cs}} \end{aligned}$$

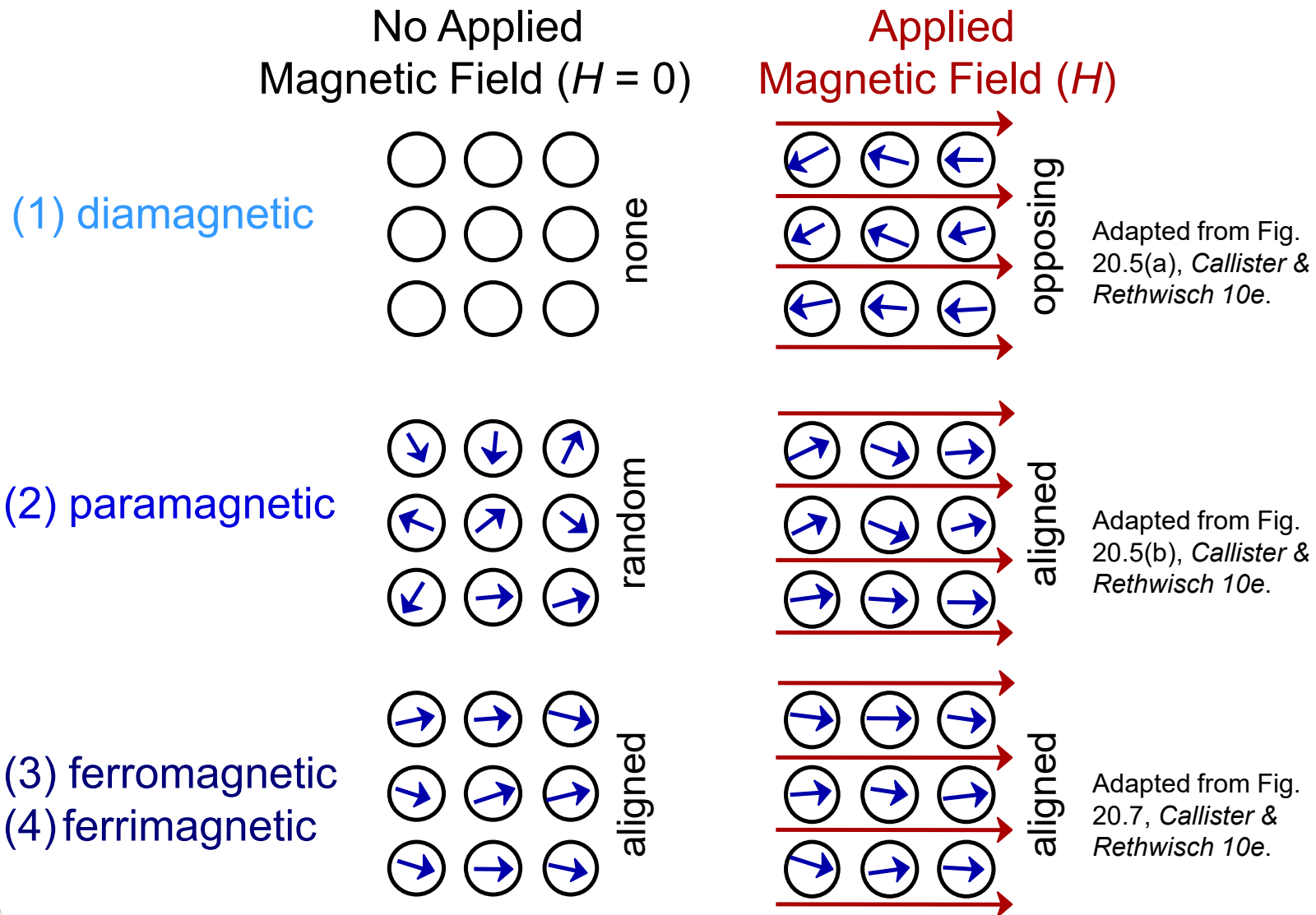
Types of Magnetism



Plot adapted from Fig. 20.6, *Callister & Rethwisch 10e.*
 Values and materials from Table 20.2, *Callister & Rethwisch 10e.*



Magnetic Responses for 4 Types



Domains in Ferromagnetic & Ferrimagnetic Materials

- As the applied field (H) increases the magnetic domains change shape and size by movement of domain boundaries.

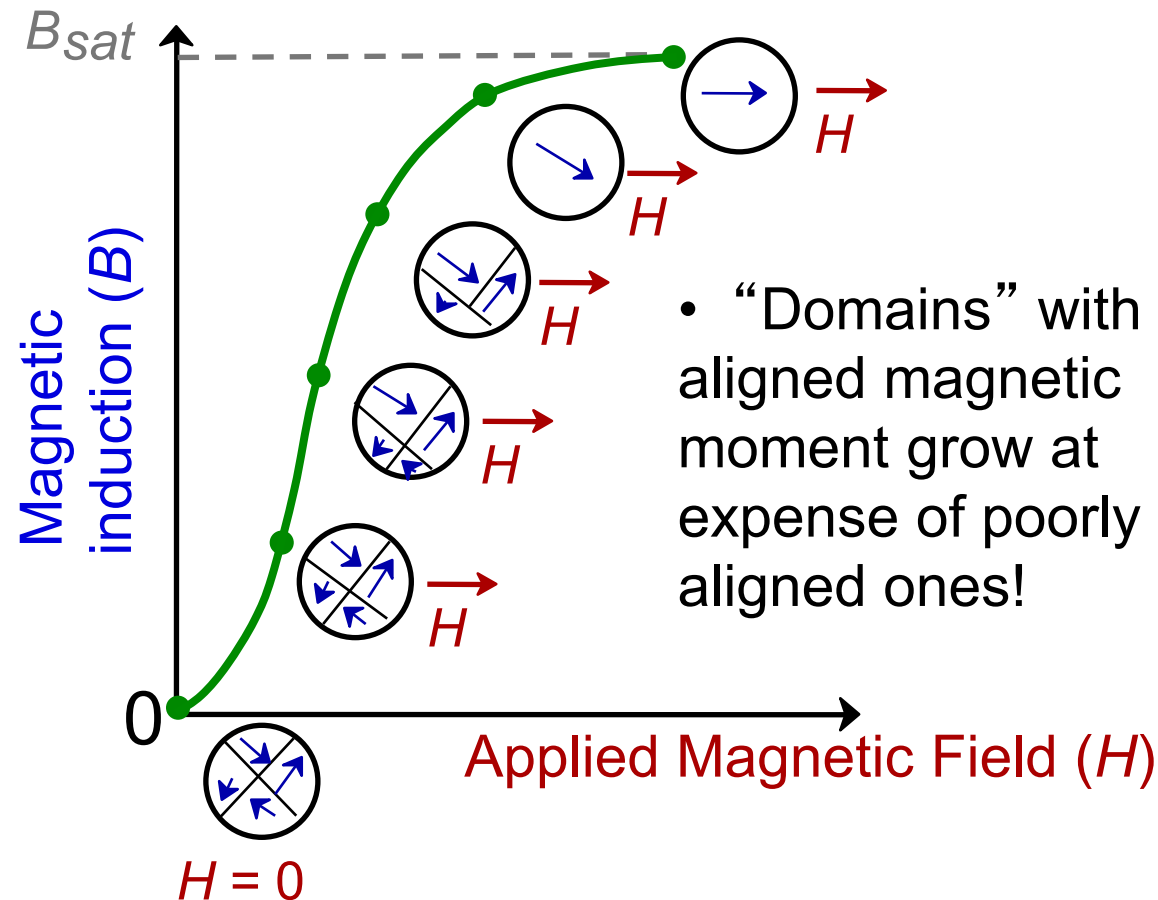
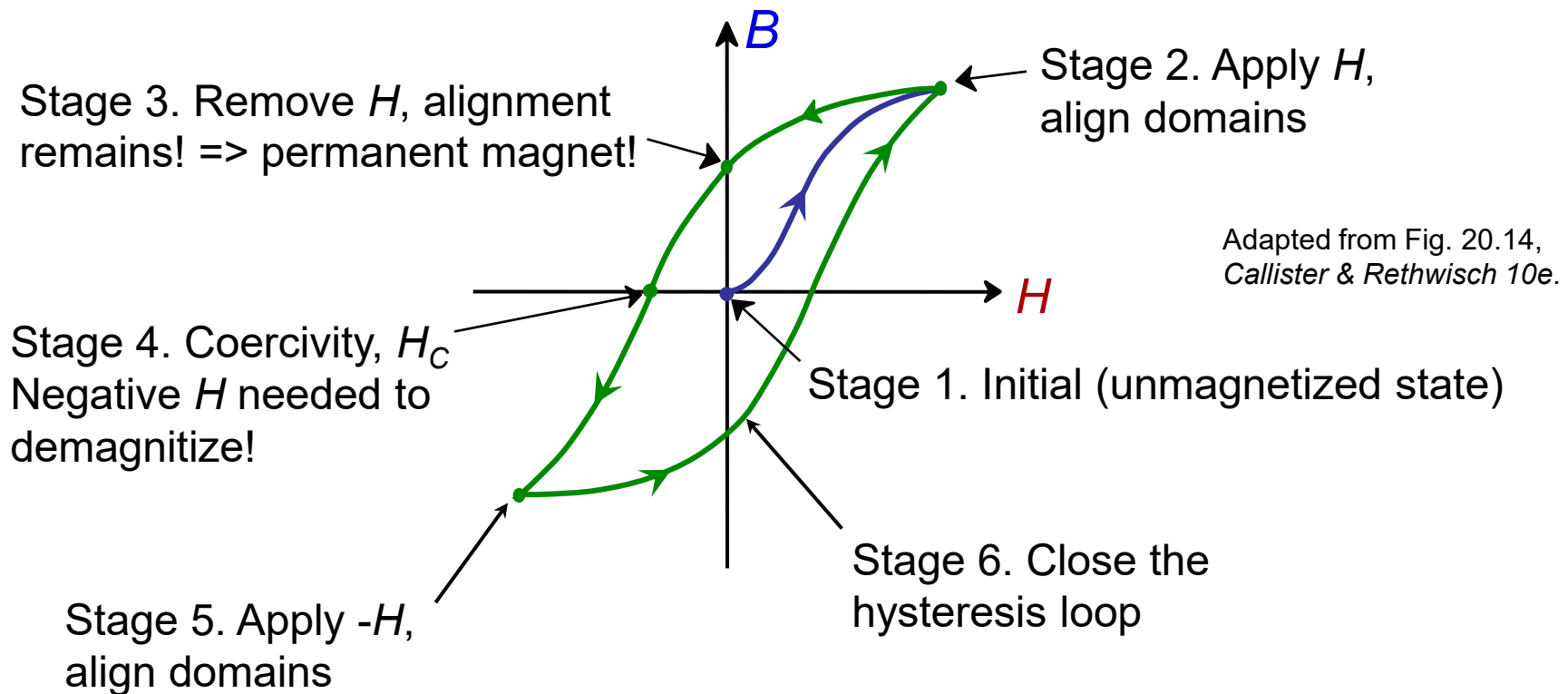


Fig. 20.13, Callister & Rethwisch 10e.

Hysteresis and Permanent Magnetization

- The magnetic hysteresis phenomenon



Hard and Soft Magnetic Materials

Hard magnetic materials:

- large coercivities
- used for permanent magnets
- add particles/voids to inhibit domain wall motion
- example: tungsten steel --
 $H_c = 5900$ amp-turn/m)

Soft magnetic materials:

- small coercivities
- used for electric motors
- example: commercial iron 99.95 Fe

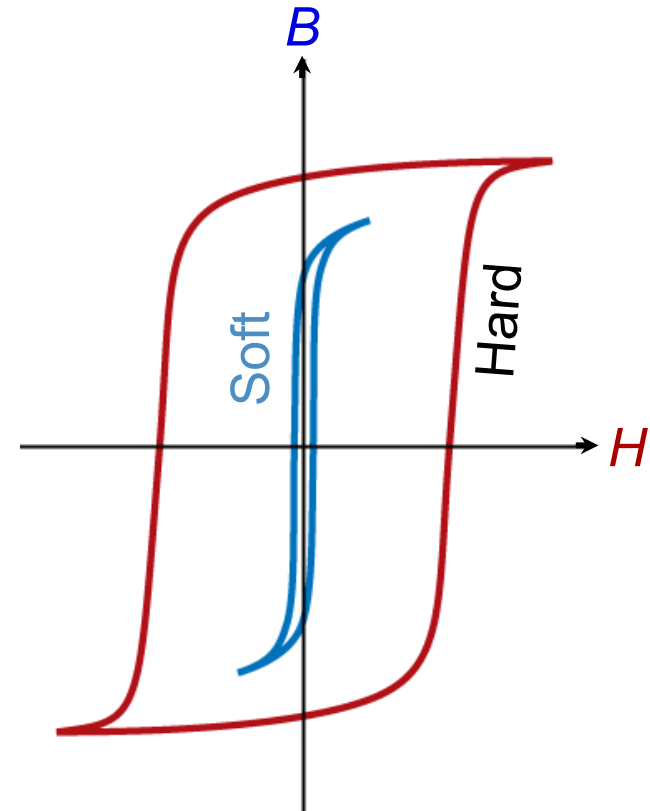


Fig. 20.19, *Callister & Rethwisch 10e*.
(From K. M. Ralls, T. H. Courtney, and
J. Wulff, *Introduction to Materials Science
and Engineering*. Copyright © 1976 by
John Wiley & Sons, New York. Reprinted by
permission of John Wiley & Sons, Inc.)

Magnetic Storage

- Digitized data in the form of electrical signals are transferred to and recorded digitally on a magnetic medium (tape or disk)
- This transference is accomplished by a recording system that consists of a **read/write head**
 - **“write”** or record data by applying a magnetic field that aligns domains in small regions of the **recording medium**
 - **“read”** or retrieve data from medium by sensing changes in magnetization

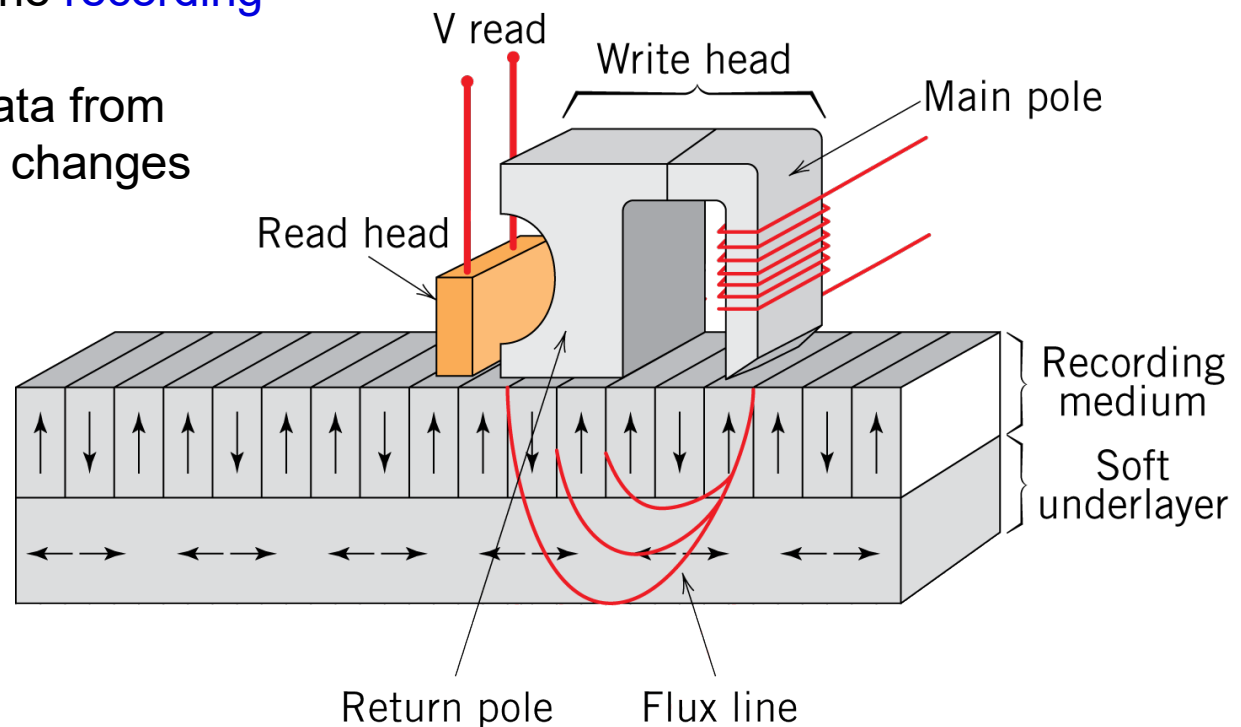


Fig. 20.23, *Callister & Rethwisch 10e.*
(Courtesy of HGST, a Western Digital Company.)

Magnetic Storage Media Types

- Hard disk drives (**granular/perpendicular media**):

- CoCr alloy grains (darker regions) separated by oxide grain boundary segregant layer (lighter regions)
- Magnetization direction of each grain is perpendicular to plane of disk

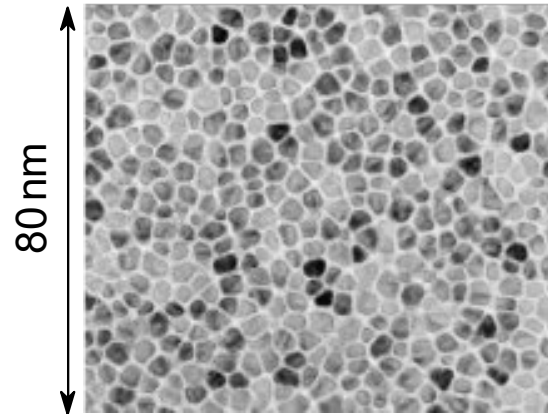
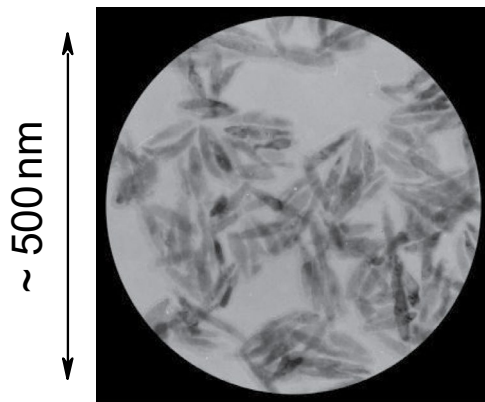
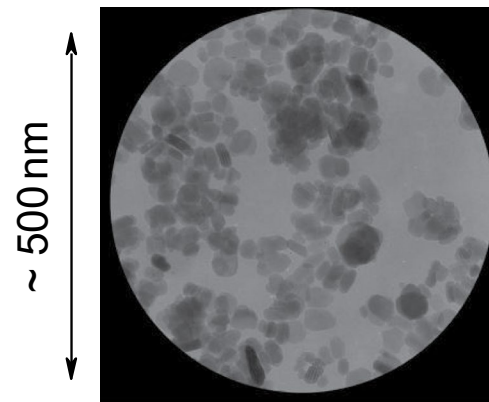


Fig. 20.24, *Callister & Rethwisch 10e.*
(Courtesy of Seagate Recording Media)

- Recording tape (**particulate media**):



- Acicular (needle-shaped) ferromagnetic metal alloy particles



- Tabular (plate-shaped) ferrimagnetic barium-ferrite particles

Fig. 20.25, *Callister & Rethwisch 10e.*
(Courtesy of Fuji Film Inc., Recording Media Division)

Superconductivity

Found in 26 metals and hundreds of alloys & compounds

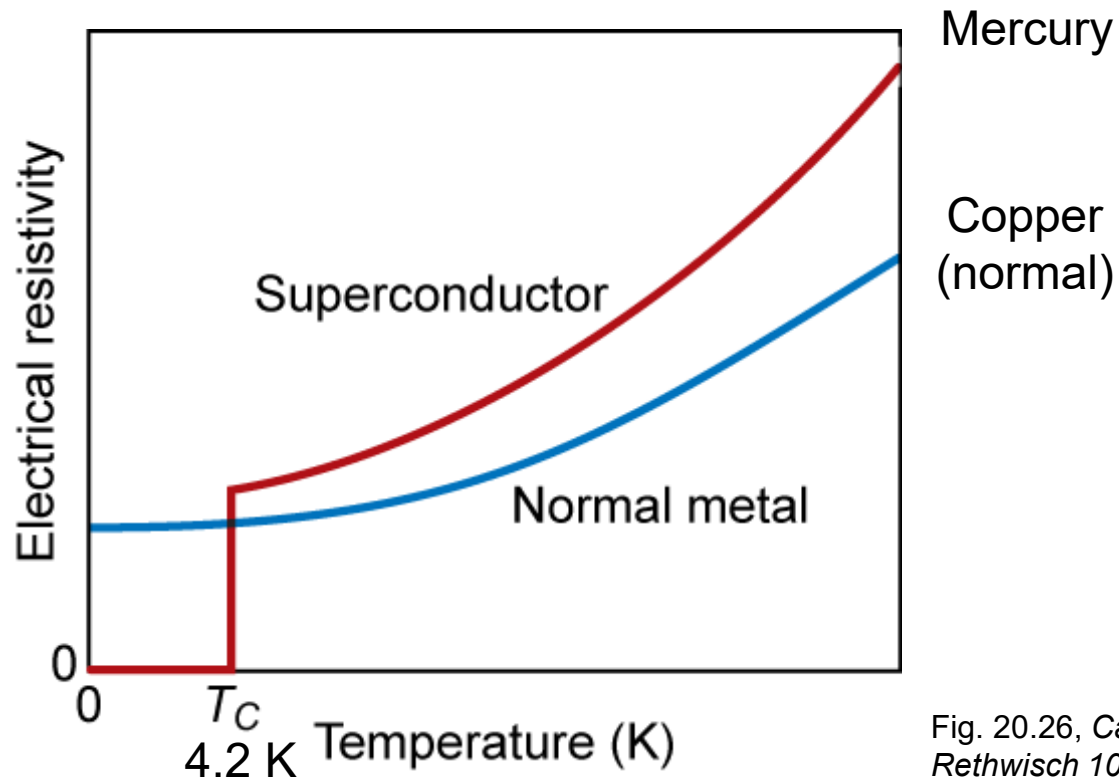


Fig. 20.26, Callister & Rethwisch 10e.

- T_C = critical temperature
= temperature below which material is superconductive



Critical Properties of Superconductive Materials

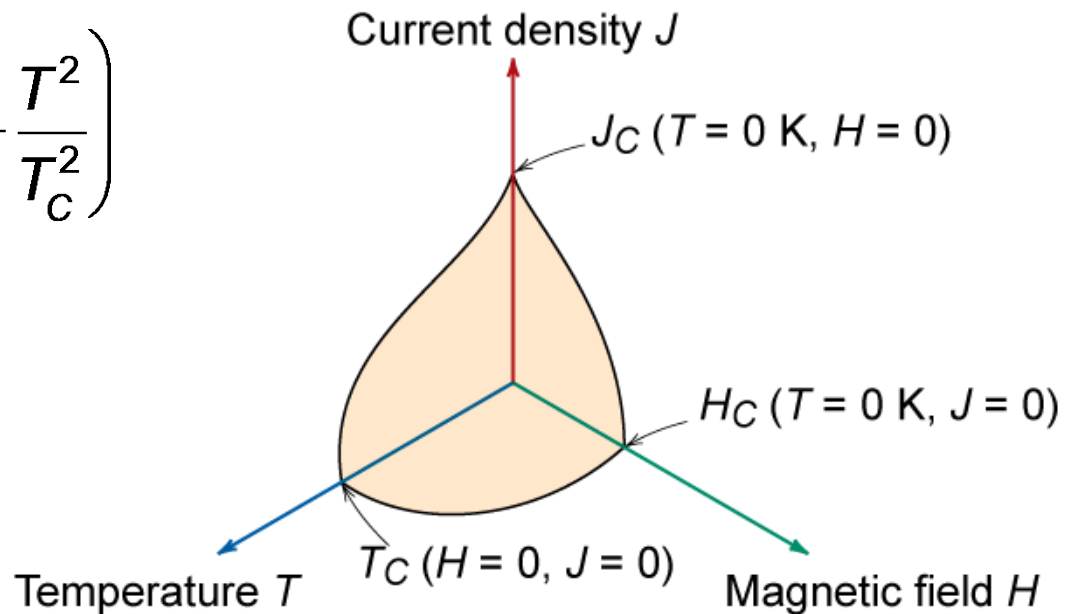
T_C = critical temperature - if $T > T_C$ not superconducting

J_C = critical current density - if $J > J_C$ not superconducting

H_C = critical magnetic field - if $H > H_C$ not superconducting

$$H_C(T) = H_C(0) \left(1 - \frac{T^2}{T_C^2} \right)$$

Fig. 20.27, Callister & Rethwisch 10e.



Meissner Effect

- Superconductors expel magnetic fields

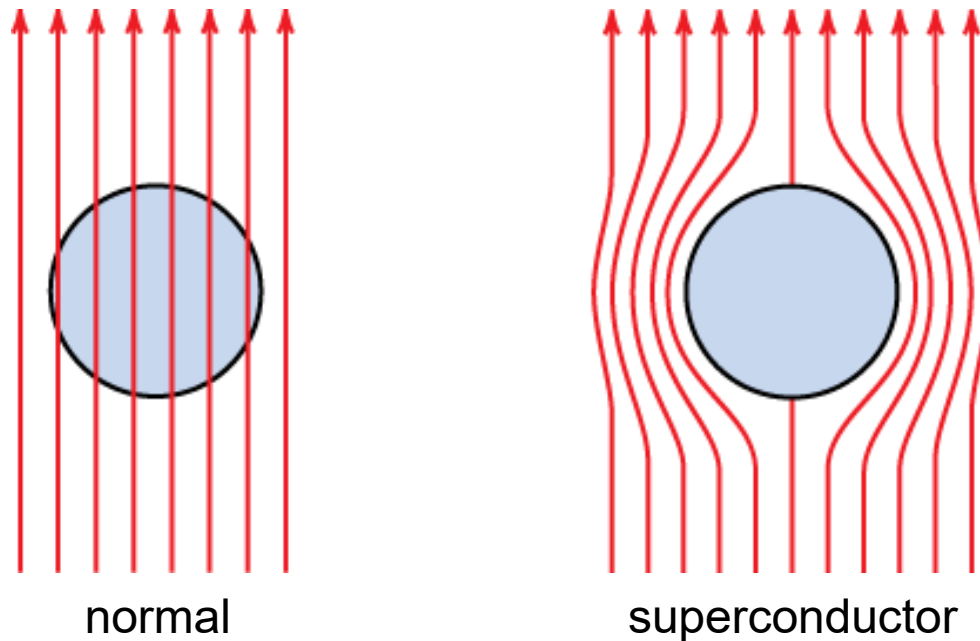
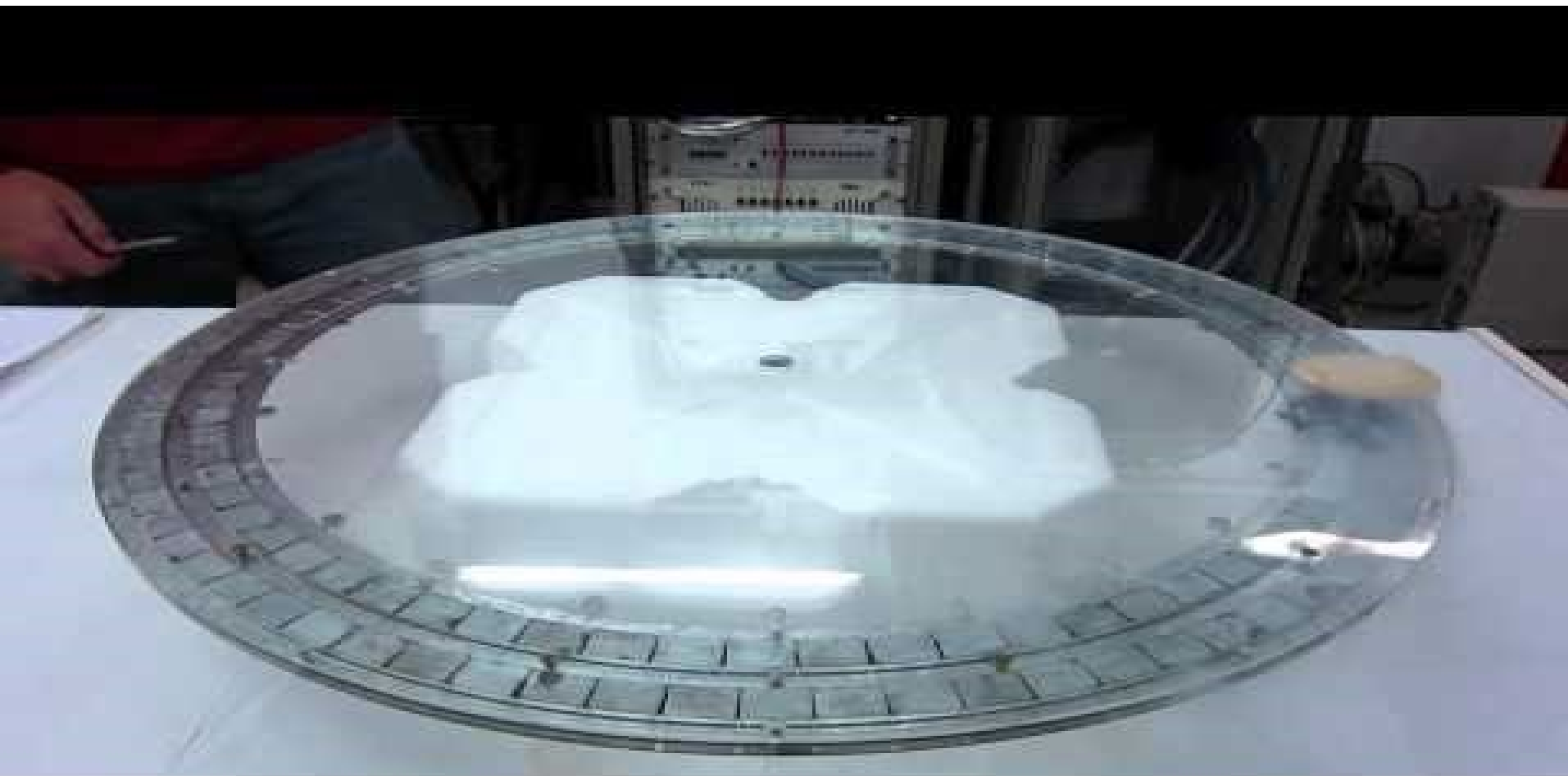


Fig. 20.28, Callister & Rethwisch 10e.

- This is why a superconductor will float above a magnet



Advances in Superconductivity

- Research in superconductive materials was stagnant for many years.
 - Everyone assumed $T_{C,max}$ was about 23 K
 - Many theories said it was impossible to increase T_C beyond this value
- 1987- new materials were discovered with $T_C > 30$ K
 - ceramics of form $Ba_{1-x}K_xBiO_{3-y}$
 - Started enormous race
 - $YBa_2Cu_3O_{7-x}$ $T_C = 90$ K
 - $Tl_2Ba_2Ca_2Cu_3O_x$ $T_C = 122$ K
 - difficult to make since oxidation state is very important
- The major problem is that these ceramic materials are inherently brittle.

