Chemical Engineering 412

Introductory Nuclear Engineering

Lecture 16 Nuclear Reactor Theory III Neutron Transport



With any major decision there are cautions and considerations to make, but once there has been illumination, beware the temptation to retreat from a good thing. If it was right when you prayed about it and trusted it and lived for it, it is right now. Don't give up when the pressure mounts. Certainly don't give in to that being who is bent on the destruction of your happiness.

Jeffrey R. Holland



Homework Notes

- Homework 15 is the OEP and a web problem, posted on the website
- Homework 16 is 2 book problems, 1 web problem.

• Both assignments are due Friday



Topics

- Group 1: Effects of Bio. On Rad Trans.
- Group 2: Frost Damage
- Group 3: Deep Time Analysis
- Group 4: Infiltration
- Group 5: Erosion of Cover
- Group 6: Clay Liner
- Group 7: GoldSim Quality Assurance
- Group 8: Evapotranspiration Cover



Monday March 5th – problem outline due

One-group Reactor Equation

Mono-energetic neutrons (Neutron Balance) $D\nabla^2 \phi - \Sigma_a \phi + s = -\frac{1}{v} \frac{\partial \phi}{\partial t}$ v is neutron speed

For reactor, $s = \nu \Sigma_f \phi$ v is neutrons/fission

In eigenfunction form and at steady state

$$D\nabla^2 \phi - \Sigma_a \phi + \frac{\nu}{k} \Sigma_f \phi = 0$$

$$\Rightarrow \nabla^2 \phi - \frac{\Sigma_a - \frac{\nu}{k} \Sigma_f}{D} \phi = \nabla^2 \phi + \frac{B^2}{B} \phi = 0$$



Material Buckling



multiplication factor = neutron generation rate/(leakage + absorption)



Fuel utilization and k_{∞}

$$s = \eta \Sigma_{aF} \phi = \eta \frac{\Sigma_{aF}}{\Sigma_a} \Sigma_a \phi = \eta f \Sigma_a \phi$$

f = fuel utilization factor – neutrons absorbed by fuel / (those absorbed by fuel + by other means – coolant, moderator, etc.)

$$k_{\infty} = \frac{\eta f \Sigma_a \phi}{\Sigma_a \phi} = \eta f$$

 $=\frac{\Sigma_{aF}}{\Sigma_{a}}$

 k_{∞} = k-value for infinite (no overall leakage) reactor – a material property





Operating Critical Reactor Equation

k = 1 Reactor operating at steady state $-DB^{2}\phi - \Sigma_{a}\phi + \frac{k_{\infty}}{k}\Sigma_{a}\phi = -\frac{1}{\nu}\frac{\partial\phi}{\partial t}$ $-DB^2\phi + (k_{\infty} - 1)\Sigma_a\phi = 0$ $-B^2\phi + (k_{\infty} - 1)\frac{\Sigma_a}{D}\phi = -B^2\phi + \frac{(k_{\infty} - 1)}{L^2}\phi = 0$ $L^2 = \frac{D}{\Sigma_a}$ One-group diffusion area $B^2 = \frac{k_{\infty} - 1}{I^2}$ One-group buckling

Perspective

- Previous equations show
 - how to solve for neutron flux profile ϕ as a function of space
 - How to determine critical reactor dimensions

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$$B^2 = \frac{k_{\infty}-1}{L^2} = \frac{(k_{\infty}-1)\Sigma_a}{D}$$
, for a bare reactor $(B_g^2=B_{mat}^2)$

- First find solutions to the reactor equations
 - 1D, 2D, or 3D
 - Then find dimensions for a critical reactor
- Assumptions:
 - Bare, homogeneous reactors
 - Constant (special and temporal) properties
 - None are valid but, but help to develop insight into reactor operations
- Because source terms are proportional to the flux, the generally inhomogeneous differential equations are now homogeneous equations.



Bare Slab Reactor Solution



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The constant A is as yet undetermined and relates In to the power. There are different solutions to this problem for every power level.

Infinite plane indicates no net flux from sides

Bare Slab Reactor Power



Infinite plane indicates no net flux from sides



Spherical Reactor



Spherical Reactor Power

Integrate over 2 symmetric dimensions –
transform volume integral to radial integral

$$P = E_R \Sigma_f \iiint \phi(r) dV = 4\pi E_R \Sigma_f \int_0^R r^2 \phi(r) dr$$

$$P = 4\pi E_R \Sigma_f A \frac{\tilde{R}}{\pi} \left[\frac{\tilde{R}}{\pi} \sin\left(\frac{\pi R}{\tilde{R}}\right) - R \cos\left(\frac{\pi R}{\tilde{R}}\right) \right]$$
again, power is proportional to
flux and highest at center

$$\phi(r) = \frac{P \sin\left(\frac{\pi r}{\tilde{R}}\right)}{4 E_R \Sigma_f R^2 r}$$

Infinite Cylindrical Reactor

$$\frac{1}{r}\frac{d}{dr}\left(r\frac{d\phi}{dr}\right) = -B^{2}\phi = \frac{d^{2}\phi}{dr^{2}} + \frac{1}{r}\frac{d\phi}{dr}$$

$$\phi(\tilde{R}) = \phi'(0) = 0; |\phi(r)| < \infty$$

$$\frac{d^{2}\phi}{dr^{2}} + \frac{1}{r}\frac{d\phi}{dr} + \left(B^{2} - \frac{m^{2}}{r^{2}}\right)\phi = 0$$

$$\phi(r) = AJ_{0}(Br) + CY_{0}(Br)$$

$$B_{n} = \frac{x_{n}}{\tilde{R}}$$

$$R_{1} = \left(\frac{x_{1}}{\tilde{R}}\right)^{2} = \left(\frac{2.405}{\tilde{R}}\right)^{2}$$

$$\phi(r) = AJ_{0}\left(\frac{2.405}{\tilde{R}}r\right)$$
production

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reactor transport equation

boundary conditions

zero-order (m=0) Bessel equation

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general solution involves Bessel functions of first and second kind

flux is finite

roots of Bessel functions - ϕ is zero at boundary \tilde{R}

first root

solution (power roduction determines A)



Bessel Functions



Infinite Cylindrical Reactor Power

$$P = E_R \Sigma_f \iiint \phi(r) dV = 2\pi E_R \Sigma_f \int_0^R r \phi(r) dr$$
transform volume
integral to radial
integral -
becomes power
per unit length

$$\int_0^R x' J_0(x') dx' = x J_1(x)$$

$$P = \frac{2\pi E_R \Sigma_f R^2 A J_1(2.405)}{2.405}$$

$$\phi(r) = \frac{0.738P}{E_R \Sigma_f R^2} J_0\left(\frac{2.405r}{R}\right)$$



again, power is proportional to power and highest at center

Finite Cylindrical Reactor

$$\frac{1}{r}\frac{\partial}{\partial r}\left(\frac{\partial\phi}{\partial r}\right) + \frac{\partial^{2}\phi}{\partial z^{2}} = -B^{2}\phi \qquad \text{reactor transport equation}$$

$$\phi\left(\tilde{R}, z\right) = \phi'(0, z) = \phi\left(r, \frac{\tilde{H}}{2}\right) = \phi\left(r, -\frac{\tilde{H}}{2}\right) = 0 \qquad \text{boundary conditions}$$

$$\phi\left(r, z\right) = R(r)Z(z) \qquad \text{separation of variables}$$

$$\frac{1}{r}\frac{\partial}{\partial r}\left(\frac{\partial\phi}{\partial r}\right) + \frac{\partial^{2}\phi}{\partial z^{2}} = \frac{Z}{r}\frac{\partial}{\partial r}\left(\frac{\partial R}{\partial r}\right) + R\frac{\partial^{2}Z}{\partial z^{2}}R = -B^{2}R(r)Z(z)$$

$$\frac{1}{R}\frac{\partial}{\partial r}\left(\frac{\partial R}{\partial r}\right) + \frac{1}{Z}\frac{\partial^{2}Z}{\partial z^{2}}R = -B^{2}$$

$$\stackrel{\tilde{R}}{\text{since } R \text{ and } Z \text{ vary independently, both portions of the equation must equal (generally different) constants, designated as B_{R} and B_{Z} , respectively$$

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Finite Cylinder Solution

solution is the product of the infinite cylinder and infinite slab solutions Buckling is higher than for either the infinite plane or the infinite cylinder. Buckling generally increases with increasing leakage, and there are more surfaces to leak here than either of the infinite cases.

Neutron Flux Contours

Neutron flux in finite cylindrical reactor



3D contours of neutron flux at high power







3D contours of neutron flux at low power

Bare Reactor Summary





Some details

- Reflected reactors lend themselves less easily to analytical solution – commonly reactors are considered as sphere equivalents rather than trying to solve the equations.
- Reasonable representation for fast neutrons – not for thermal reactors
- Reflector savings in size is typically about the thickness of the extrapolated distance.



Flux Comparisons



Distance from center of reactor



Thermal Flux Variations



