

Lecture 13 - curve fitting & interpolation

Class Business

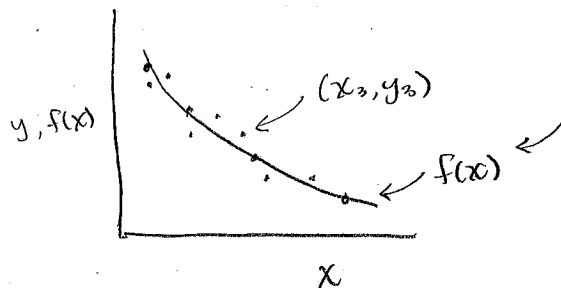
- * prayer / spiritual thought
- * announcements
- * unit of the day

$$1 \text{ hp} = 745.7 \text{ W}$$

I. Curve Fitting vs. Interpolation

A. Curve Fitting

* Recall that in curve fitting, we have data $\{x_i, y_i\}$, and we are trying to find a model $f(x)$ that best fits the data.



usually we know a form of $f(x)$ and we vary some parameters.

e.g. $f(x) = ax + b$,
vary a, b for best fit.

* We fit the model assuming the spread is from noise:

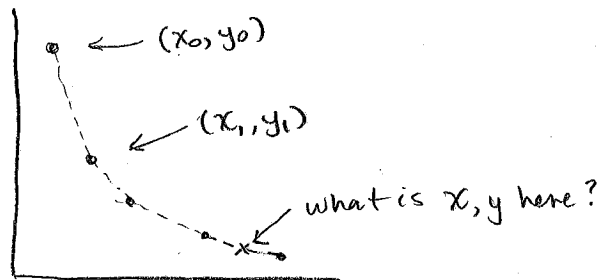
$$y_i = f(x_i) + \epsilon_i$$

$\uparrow$ $\nwarrow$ $\nwarrow$
 data model noise

* In curve fitting we are trying to find one function that approximately fits all of the data.

B. Interpolation

- * In interpolation, we have some data $\{x_i, y_i\}$ at discrete points, and we want to know the value of y for some x not in our data set.



- * In interpolation, we don't have an underlying model, and we assume that the noise is negligible
- * In interpolation we fit many piecewise functions that exactly fits all of the data.

Examples in python file

- * Polynomial uniqueness theorem - can exactly fit an n th order polynomial with $n+1$ points

e.g.
 line with 2 points
 quadratic with 3 points
 cubic with 4 points
 etc.

- * Runge's phenomenon - why can't we use just one polynomial? It oscillates wildly. Will need piecewise polynomials

• R-oo-ng-a
 rhymes w/ roomba

* spline - a piecewise, polynomial interpolation scheme that exactly fits every data point.

e.g. linear spline (linear interpolation)

quadratic spline

⑧ cubic spline ← has continuous 1st & 2nd derivatives.

Practice: Curve fit or Interpolate

II. Curve Fitting & Interpolation in Python

See Examples in python file

A. Curve fitting

* `numpy.polyfit()` & `numpy.polyval()`

- linear least squares of a polynomial
- equivalent to LINEST in Excel

* `scipy.optimize.curve_fit()`

- general, non-linear least squares
- equivalent to minimizing the sum of squared error using solver.

* R^2 : get by hand

$$R^2 = 1 - \frac{SSE}{SST}$$

$$SSE = \sum_i [y_i - f(x_i)]^2$$

$$SST = \sum_i [y_i - \bar{y}]^2$$

B. Interpolation

* `scipy.interpolate.interp1d()`

- 'linear', 'quadratic', 'cubic'

Practice

- Polynomial, linear least-squares
- Non-linear least-squares
- R^2
- Spline interpolation