

Lecture 21 - ODEs and Explicit Euler

Outline

I. Introduction to Differential Equations

- * In an ODEs course (Math 333/334) you cover analytical methods for solving ODEs
- Numerical Methods are quite different.

* What is a differential equation?

→ Any equation w/ derivatives in it!

ex. $m \frac{d^2x}{dt^2} = F$ (Newton's 2nd law) } super common in physical sciences

$x(t)$ $\leftarrow$ $\frac{dc}{dt} = -k c^2$ (2nd order chem rxn)

$c(t)$

* How classify DEs? → Give us a language to be able to talk about.

• Order: The number order of the highest derivative

$m \frac{d^2x}{dt^2} = F \rightarrow$ 2nd order D.E. (2nd derivative)

$\frac{dc}{dt} = -k c^2 \rightarrow$ 1st order D.E. (1st order derivative)

$\frac{d^2x}{dt^2} + \frac{dx}{dt} - x^2 = 5$? (2nd order)

• Linearity: Just like algebraic equations, DEs can be linear or nonlinear. In DE class → stick to linear.

$m \frac{d^2x}{dt^2} = F$ (linear) no powers of terms w/ x in them

$\frac{dc}{dt} = -k c^2$ (non-linear) $x(t) \rightarrow x(t)^2$

$\frac{d}{dt} \left(\frac{dx}{dt} \right)$ $\left(\frac{dx}{dt} \right)^2$ or $x \cdot \frac{dx}{dt}$

$\frac{d}{dt} (cx + by) \rightarrow c \frac{dx}{dt} + b \frac{dy}{dt}$ (ok) $\frac{d}{dt} (cx + by) \rightarrow$

$y \frac{dy}{dt} + 5 = 0$ (non linear)

$\frac{dy}{dt} = -t^2$ (linear)

- Ordinary vs. Partial DEs : an ordinary DE (ODE) has derivatives w.r.t only one variable. while a Partial D.E. has derivatives w.r.t. more than one variable

$$\begin{array}{lcl} \text{reg. derivatives} \rightarrow \frac{dc}{dt} = -kc^2 & & \frac{d}{dt} \rightarrow c(t) \text{ only} \\ \text{Partial derivatives} \rightarrow \frac{\partial^2 c}{\partial x^2} + \frac{\partial^2 c}{\partial y^2} = 0 & & \text{O.D.E.} \\ & & c(x,y) \rightarrow \frac{\partial^2}{\partial x^2}, \frac{\partial^2}{\partial y^2} \\ & & \text{P.D.E.} \end{array}$$

Goal: $c(t) = ?$ $c(x,y) = ?$

- Initial / boundary conditions : All DEs need auxiliary conditions to find a unique solution

think about this:

$$\begin{array}{l} \frac{dx}{dt} = v \leftarrow \text{constant} \\ \text{speed} \rightarrow \end{array} \quad \begin{array}{l} \text{separate \& integrate} \\ \text{(indef. integral)} \end{array}$$

$$x = \int v dt = vt + C$$

$\uparrow$
const

$x(t=0) = v \cdot 0 + C$
 $\uparrow$
 x_0

$x_0 = C = 2$

- you need an auxiliary condition to specify a unique solution

- you need one condition for each order of derivative

$$\begin{array}{lcl} \frac{dx}{dt} = v \rightarrow x_0 & & \frac{d^2x}{dt^2} = -g \rightarrow \begin{array}{l} x_0 - \text{initial pos} \\ v_0 - \text{initial vel.} \end{array} \\ \uparrow & & \uparrow \\ 1 & & 2 \end{array}$$

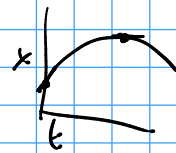
2 conditions

$$\frac{d^3x}{dt^3} + \frac{dx}{dt} + 5 = -2$$

- Initial conditions are specified at the same point.

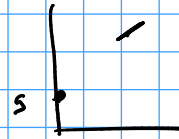
$$\begin{array}{lcl} \frac{dx}{dt} = v & x(t=0) = 2 & \frac{d^2x}{dt^2} = -g \\ \uparrow & \uparrow \text{initial condition} & \downarrow \\ & & x(t=0) = 5 \\ & & \frac{dx}{dt}(t=0) = 2 \\ & & \text{initial conditions} \end{array}$$

$$\frac{d^2x}{dt^2} = -g \quad x(t=5) = 5 \quad \frac{dx}{dt}(t=5) = 2 \rightarrow \text{also initial conditions!}$$



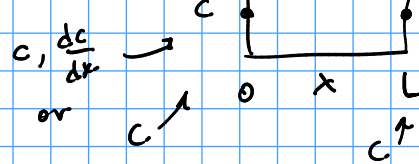
A boundary condition is anything else,
c.e. when conditions are at separate points

$$\frac{d^2x}{dt^2} = -g \quad x(t=0) = 5 \quad \frac{dx}{dt}(t=5) = 2$$



specified at different points $\rightarrow$ Boundary condition

$$\frac{d^2c}{dx^2} = 2$$



specify c at 2 pts
not $\frac{dc}{dx}$ at 1 pt.

B.C are harder.

- problems w/ I.C's are called initial value problems $\rightarrow$ IVPs
- " " B.C's " " Boundary value problems $\rightarrow$ BVPs

$\Rightarrow$ Forces: any order, non-linear (or linear)
ODEs, IVPs

In Mech: any order (2nd or less), linear, ODEs, IVPs
dept (1 week of BVPs)

$\uparrow$
case of nonlinear
(1st order only)

II. The Explicit Euler method

* ODEs, $\rightarrow$ today 1st order ODE, IVP.

* A single first order IVP has the form:

$$\frac{dy}{dt} = f(y, t), \quad y(0) = y_0$$

"rate equation" $\leftarrow$ "speed"
LHS: rate of change of y
RHS: function
IC: initial "position"

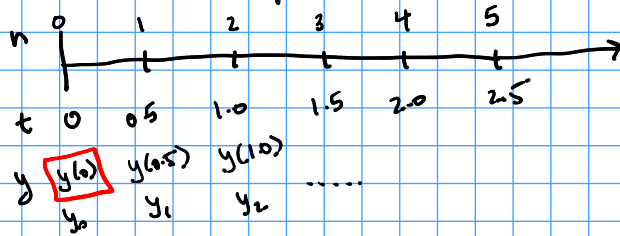
* How solve? "Explicit Euler" method.

(i) Make a discrete time grid.

(ii) approximate the derivative on this grid

(iii) use grid & derivative to rewrite the ODE.

(i) Make a discrete grid



$$\frac{dy}{dt} = f(y, t)$$

$$y(t=0) = y_0$$

(ii) approx the derivative on my grid

$$\frac{dy}{dt} \approx \frac{\Delta y}{\Delta t} \approx \frac{y_{n+1} - y_n}{t_{n+1} - t_n} \quad \text{eg.} \quad \frac{y_1 - y_0}{t_1 - t_0}$$

(iii) Put (i) & (ii) together into $\square$

$$\frac{y_{n+1} - y_n}{t_{n+1} - t_n} = f(y_n, t_n) \quad \text{ex} \quad \frac{y_1 - y_0}{t_1 - t_0} = f(y_0, t_0)$$

$$t_{n+1} - t_n = \Delta t$$

$$y_{n+1} = y_n + \underbrace{(t_{n+1} - t_n)}_{\Delta t} \cdot f(y_n, t_n)$$

$$y_{n+1} = y_n + \Delta t \cdot f(y_n, t_n)$$

Explicit Euler method

III. Example. to code in Python & Excel.

1st order
ODE
ICP

$$\begin{cases} \frac{dc}{dt} = -\frac{c}{\tau} \\ c(0) = c_0 \end{cases}$$

$$\tau = 0.6$$

$$c_0 = 1$$

$$\frac{dc}{dt} = f(t, c) = -\frac{c}{\tau}$$

$$\frac{c_{n+1} - c_n}{\Delta t} = -\frac{c_n}{\tau} \rightarrow c_{n+1} = c_n + \Delta t \cdot \left(-\frac{c_n}{\tau}\right)$$

$$c_{n+1} = c_n - \frac{\Delta t c_n}{\tau} = c_n \left(1 - \frac{\Delta t}{\tau}\right)$$

can solve by hand.
 $c = c_0 e^{-t/\tau}$