

Vector Products in curvilinear coordinates

What is $\underline{v} \cdot \underline{w}$ in curvilinear coordinates?

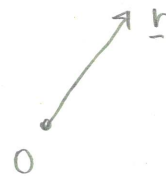
* The dot product is given by

$$\underline{v} \cdot \underline{w} = \sum_i v_i w_i$$

for any orthogonal coordinate system. A similar result holds for other products.

* Be careful. This does not apply to products of position vectors. Position vectors are given by:

$$\underline{r} = x \underline{e}_x + y \underline{e}_y + z \underline{e}_z$$

Example 1: Regular dot product of field variables

Consider the velocity field in cylindrical coordinates

$$\underline{v} = v_r \underline{e}_r + v_\theta \underline{e}_\theta$$

$$v_r = u \cos \theta \left[1 - \left(\frac{R}{r} \right)^2 \right]$$

$$v_\theta = -u \sin \theta \left[1 + \left(\frac{R}{r} \right)^2 \right]$$

Flow at high Re around a cylinder



(a) In cylindrical coordinates

$$\underline{v} \cdot \underline{v} = v_r^2 + v_\theta^2$$

$$v_r^2 = u^2 \cos^2 \theta \left[1 - \left(\frac{R}{r} \right)^2 \right]^2$$

$$v_\theta^2 = u^2 \sin^2 \theta \left[1 + \left(\frac{R}{r} \right)^2 \right]^2$$

$$\begin{aligned} v^2 = v_r^2 + v_\theta^2 &= u^2 \cos^2 \theta \left[1 - 2\left(\frac{R}{r}\right)^2 + \left(\frac{R}{r}\right)^4 \right] \\ &\quad + u^2 \sin^2 \theta \left[1 + 2\left(\frac{R}{r}\right)^2 + \left(\frac{R}{r}\right)^4 \right] \\ &= u^2 (\cos^2 \theta + \sin^2 \theta) \left[1 + \left(\frac{R}{r}\right)^4 \right] \\ &\quad + u^2 (\sin^2 \theta - \cos^2 \theta) (2) \left(\frac{R}{r}\right)^2 \end{aligned}$$

$$\text{recall: } \cos^2 \theta + \sin^2 \theta = 1$$

$$\cos^2 \theta - \sin^2 \theta = \cos 2\theta$$

$$\boxed{\frac{v^2}{u^2} = 1 + 2\left(\frac{R}{r}\right)^2 \cos(2\theta) + \left(\frac{R}{r}\right)^4}$$

(b) In Cartesian coordinates

* Convert to cartesian coordinates first

$$\begin{aligned} \underline{e}_r &= \cos \theta \underline{e}_x + \sin \theta \underline{e}_y \\ \underline{e}_\theta &= -\sin \theta \underline{e}_x + \cos \theta \underline{e}_y \end{aligned} \quad \left. \vphantom{\begin{aligned} \underline{e}_r &= \cos \theta \underline{e}_x + \sin \theta \underline{e}_y \\ \underline{e}_\theta &= -\sin \theta \underline{e}_x + \cos \theta \underline{e}_y \end{aligned}} \right\} \begin{array}{l} \text{relation between} \\ \text{unit vectors} \end{array}$$

$$\underline{v} = v_x \underline{e}_x + v_y \underline{e}_y = v_r \underline{e}_r + v_\theta \underline{e}_\theta$$

$$= u \cos \theta \left[1 - \left(\frac{R}{r} \right)^2 \right] \times \underbrace{(\cos \theta \underline{e}_x + \sin \theta \underline{e}_y)}_{\substack{\text{write this and} \\ \text{sub in } \underline{e}_r \text{ and } \underline{e}_\theta}}$$

$$- u \sin \theta \left[1 + \left(\frac{R}{r} \right)^2 \right] (-\sin \theta \underline{e}_x + \cos \theta \underline{e}_y)$$

$$\begin{aligned} &= u \cos^2 \theta \left[1 - \left(\frac{R}{r} \right)^2 \right] \underline{e}_x + u \cos \theta \sin \theta \left[1 - \left(\frac{R}{r} \right)^2 \right] \underline{e}_y \\ &\quad + u \sin^2 \theta \left[1 + \left(\frac{R}{r} \right)^2 \right] \underline{e}_x - u \cos \theta \sin \theta \left[1 + \left(\frac{R}{r} \right)^2 \right] \underline{e}_y \end{aligned}$$

$$v_x = u \cos^2 \theta \left[1 - \left(\frac{R}{r} \right)^2 \right] + u \sin^2 \theta \left[1 + \left(\frac{R}{r} \right)^2 \right]$$

$$v_y = u \cos \theta \sin \theta \left[1 - \left(\frac{R}{r}\right)^2 - 1 - \left(\frac{R}{r}\right)^2 \right]$$

↓ simplify both

$$\begin{aligned} v_x &= u \cos^2 \theta + u \sin^2 \theta - u \cos^2 \theta \left(\frac{R}{r}\right)^2 + u \sin^2 \theta \left(\frac{R}{r}\right)^2 \\ &= u \underbrace{[\cos^2 \theta + \sin^2 \theta]}_1 - u \left(\frac{R}{r}\right)^2 \underbrace{[\cos^2 \theta - \sin^2 \theta]}_{\cos 2\theta} \end{aligned}$$

$$v_x = u - u \left(\frac{R}{r}\right)^2 \cos 2\theta \quad \checkmark$$

$$v_y = -2u \cos \theta \sin \theta \left(\frac{R}{r}\right)^2$$

Now, compute: $\underline{v} \cdot \underline{v}$

$$\begin{aligned} v^2 = \underline{v} \cdot \underline{v} &= v_x^2 + v_y^2 = u^2 \left[1 - \left(\frac{R}{r}\right)^2 \cos 2\theta \right]^2 \\ &\quad + 4u^2 \cos^2 \theta \sin^2 \theta \left(\frac{R}{r}\right)^4 \end{aligned}$$

$$\begin{aligned} &= u^2 \left[1 - 2\left(\frac{R}{r}\right)^2 \cos 2\theta + \left(\frac{R}{r}\right)^4 \cos^2 2\theta \right] \\ &\quad + 4u^2 \cos^2 \theta \sin^2 \theta \left(\frac{R}{r}\right)^4 \end{aligned}$$

$$\frac{v^2}{u^2} = 1 - 2\left(\frac{R}{r}\right)^2 \cos 2\theta + \left(\frac{R}{r}\right)^4 [\cos^2 2\theta + 4\cos^2 \theta \sin^2 \theta]$$

expand & simplify

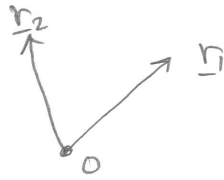
$$\begin{aligned} \cos^2(2\theta) &= (\cos^2 \theta - \sin^2 \theta)^2 = \cos^2 \theta \cos^2 \theta - 2\cos^2 \theta \sin^2 \theta \\ &\quad + \sin^2 \theta \sin^2 \theta \end{aligned}$$

$$\begin{aligned} \cos^2(2\theta) + 4\cos^2 \theta \sin^2 \theta &= \cos^2 \theta \cos^2 \theta + 2\cos^2 \theta \sin^2 \theta \\ &\quad + \sin^2 \theta \sin^2 \theta \\ &= (\cos^2 \theta + \sin^2 \theta)^2 = 1^2 = 1 \end{aligned}$$

$$\boxed{\frac{v^2}{u^2} = 1 - 2\left(\frac{R}{r}\right)^2 \cos 2\theta + \left(\frac{R}{r}\right)^4}$$

Same! The formula is correct.

Example 2: Dot product of position vectors



$$\underline{r}_1 = x_1 \underline{e}_x + y_1 \underline{e}_y + z_1 \underline{e}_z$$

$$\underline{r}_2 = x_2 \underline{e}_x + y_2 \underline{e}_y + z_2 \underline{e}_z$$

Dot product: $\underline{r}_1 \cdot \underline{r}_2 = x_1 x_2 + y_1 y_2 + z_1 z_2$

* Convert to cylindrical coordinates

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$z = z$$

$$\underline{r}_1 \cdot \underline{r}_2 = r_1 \cos \theta_1 \cdot r_2 \cos \theta_2 + r_1 \sin \theta_1 \cdot r_2 \sin \theta_2 + z_1 z_2$$

$$= r_1 r_2 (\cos \theta_1 \cos \theta_2 + \sin \theta_1 \sin \theta_2) + z_1 z_2$$

$\underbrace{\hspace{10em}}$
 $\cos(\theta_1 - \theta_2) \leftarrow \text{trig identity}$

$$\underline{r}_1 \cdot \underline{r}_2 = r_1 r_2 \cos(\theta_1 - \theta_2) + z_1 z_2$$

* Compare this to the formula valid for field variables

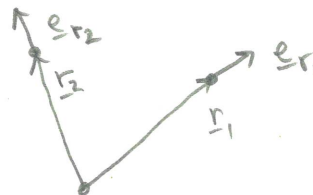
$$\underline{r}_1 = r_1 \underline{e}_r + z_1 \underline{e}_z$$

$$\underline{r}_2 = r_2 \underline{e}_r + z_2 \underline{e}_z$$

$$\underline{r}_1 \cdot \underline{r}_2 = r_1 r_2 + z_1 z_2$$

X wrong!

why? Because $\underline{e}_r$ for $\underline{r}_1$ is not the same as $\underline{e}_r$ for $\underline{r}_2$:



$$\underline{e}_r = \cos \theta \underline{e}_x + \sin \theta \underline{e}_y$$

* let's try this instead!

$$\begin{aligned}\underline{r}_1 \cdot \underline{r}_2 &= (r_1 \underline{e}_{r_1}) \cdot (r_2 \underline{e}_{r_2}) + z_1 \underline{e}_{z_1} \cdot z_2 \underline{e}_{z_2} \\ &= r_1 r_2 (\underbrace{\underline{e}_{r_1} \cdot \underline{e}_{r_2}}_{\swarrow}) + (z_1 z_2) (\underbrace{\underline{e}_{z_1} \cdot \underline{e}_{z_2}}_1)\end{aligned}$$

$$\begin{aligned}\underline{e}_{r_1} \cdot \underline{e}_{r_2} &= (\cos \theta_1 \underline{e}_x + \sin \theta_1 \underline{e}_y) \cdot (\cos \theta_2 \underline{e}_x + \sin \theta_2 \underline{e}_y) \\ &= \cos \theta_1 \cos \theta_2 + \sin \theta_1 \sin \theta_2 \\ &\quad \swarrow \text{using } \underline{e}_x \cdot \underline{e}_x = 1, \underline{e}_y \cdot \underline{e}_y = 1 \\ &\quad \quad \underline{e}_x \cdot \underline{e}_y = 0 \\ &= \cos(\theta_1 - \theta_2) \text{ (trig identity)}\end{aligned}$$

$\underline{r}_1 \cdot \underline{r}_2 = r_1 r_2 \cos(\theta_1 - \theta_2) + z_1 z_2$

This is correct!

* Moral of the story: when in doubt, use cartesian coordinates
For position vectors, be very careful! They are not
the same if they are at different points in space.